

# Programmable Logic

## Controller

## Specification

### Overview

Honeywell's new ML50 compact PLC, with its innovative architecture combines power and versatility to help provide performance in a slim, compact and affordable solution. With its high performance and functionality, the new ML50 PLC offer economical automation platform for many industrial control applications. The ML50 family can be used just as I/O, as a standalone PLC or as a distributed control. It offers broad selection of Base modules, Expansion I/O modules, various network interface options and some special modules to enhance control capabilities.

### Features

#### • Easiness and Convenience

ML50 series offers convenient user interface with various network diagnosis & monitoring functions and back-up functions.

- Enhanced user interface
- Various monitoring functions
- Network diagnosis & monitoring
- Battery less back-up

#### • Compactness

ML50 series is very compact but provides powerful functions and performance. Compact & Powerful performance is ML50's steadfast competitiveness.

#### • Functionality

With its powerful and various built-in functions, ML series can provide optimum solution for your automation task.

- Communication: RS232, RS485
- 2-axis positioning functions

**S type****H types (New)**

- High speed counter
- PID Control
- Various input processing like pulse catch, input filter
- RTC (Real Time Clock) : H type

#### • High performance

With its high-speed processing and system capability, ML50 series offers utmost efficiency for your applications.

- 83ns/step (H type) and 160ns/step (S type) processing speed and floating-point arithmetic with on-board CPU
- Up to 7 expansion modules for S type and Up to 10 expansion modules for H type, 480 I/O point control for S type and max. 704 I/O point control for H type – PLC system for low-to-mid level applications
- Up to 5 communication ports with built-in-functions and expansion modules

#### • Integrated programming & debug environment

ML50 series offers enhanced programming convenience and various monitoring / diagnosis functions.

- Programming flexibility with max 715 instructions (28 basic instructions, 677 application instructions for S type and 28 basic instructions, 687 application instructions for H type)
- Multi-PLC, Multi-program management integrated network setting monitoring & diagnosis
- Convenient variable editing
- Compatibility with Microsoft Excel
- Address, Special module & Custom event monitoring Trend monitor
- Downloading configuration via USB port (H type)

#### • Easy Expansion

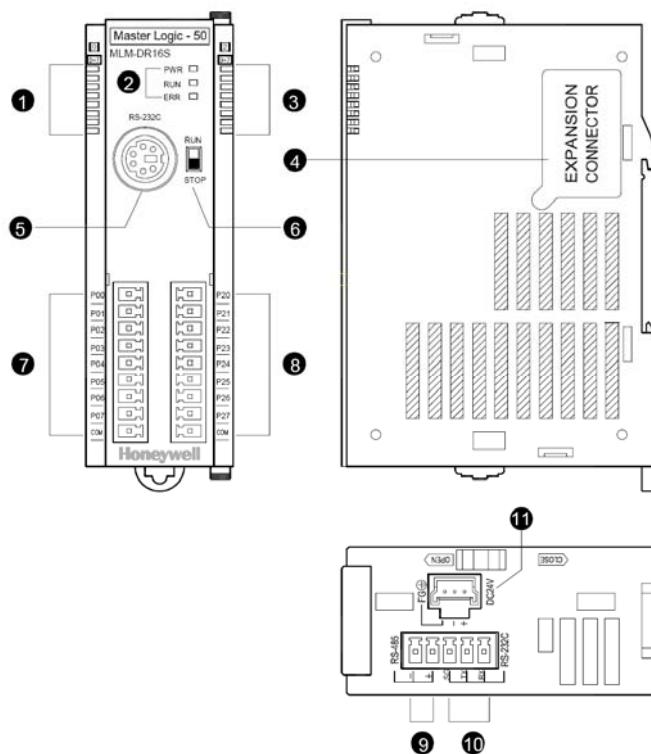
With its detachable terminal block and MIL connector, ML50 provides easy and convenient way for wiring and module change. For expansion of PLC system, each expansion module can be easily connected and separated by its direct-insert method.

## Specifications (MLM-DR16S, MLM-DN16S, MLM-DN32S)

### General

Rated Power Supply Voltage	24V DC						
Inrush Current (when power supply turns on)	70 Apeak or less						
Insulation Resistance	Higher than $10^{10}\Omega$ under DC 500V megger during power terminal and PE terminal						
Withstand Voltage	500V DC for 1min across power terminal and PE terminal						
Noise Resistance (IEC61131-2)	Square wave impulse noise : +/-1,500V Electrostatic discharge : 4kV Rated electromagnetic field noise : 27 to 500MHz, 10V/m EFT/B : 2kV in Main unit, 1kV in expansion module						
Operative Limits	Ambient Temperature	0 to 55°C					
	Relative Humidity	5 to 95%RH (non-condensing)					
	Vibration Resistance (IEC61131-2)	Occasional vibration			Continuous vibration		
		Frequency	Acceleration	Pulse width	Frequency	Acceleration	Pulse width
		10 to 57Hz	-	0.075mm	10 to 57Hz	-	0.035mm
		57 to 150Hz	9.8m/s <sup>2</sup>	-	57 to 150Hz	4.9m/s <sup>2</sup>	-
		10 times each direction(X, Y and Z)					
	Shock Resistance (IEC61131-2)	Peak Acceleration: 147 m/s <sup>2</sup> (15g) Duration: 11ms Pulse waveform: Half-sine, 3 times each direction per each axis					
Transportation & Storage	Ambient temperature	-20 to +70 °C					
	Relative Humidity	5 to +95% RH (non-condensing)					
Pollution Level	$\leq 2$  Pollution level indicates the degree to which conductive material is generated in the environment where the equipment is used. Pollution level 2 is the condition that only non-conductive pollution occurred but temporary conductivity may be produced due to condensing.						
Operating Ambience	Free from corrosive gases and excessive dust						
Altitude	Up to 2,000 meters(6,561.68 feet)						
Cooling	Air-cooling						
Base Module (unit: $\frac{mm}{inch}$ )	$\frac{30.0}{1.181} (W) \times \frac{90.0}{3.543} (H) \times \frac{60.0}{2.362} (D)$						
Expansion Module (unit: $\frac{mm}{inch}$ )	$\frac{30.0}{1.181} (W) \times \frac{90.0}{3.543} (H) \times \frac{60.0}{2.362} (D)$			MLM-DN16S, MLM-DN32S MLM-DR16S			
	$\frac{20.0}{0.787} (W) \times \frac{90.0}{3.543} (H) \times \frac{60.0}{2.362} (D)$			MLE-DC __ A, MLE-TN __ A MLF- __ 04A			
	$\frac{27.0}{1.063} (W) \times \frac{90.0}{3.543} (H) \times \frac{60.0}{2.362} (D)$			MLE-RY16A			

## Indicators and Connectors



Name	Description		
1	Input LED	Input Indication	Red on/off. Input signal on/off
2	Condition LED	PWR: Power indication	Red on/off. Power on/off
		RUN : RUN indication	Green on/off. PLC RUN/STOP
		ERR : Error indication	Red on/off. PLC error. Red off. PLC normal condition
3	Output LED	Output LED	On/off. Output signal on/off.
4	Expansion Module Connector	Connection of expansion module (I/O, Special function, Communication)	
5	PDT connector	PDT connection	Connector for SoftMaster / SoftMaster-NM connection
6	Model Switch *1	Model setting	Setting RUN/STOP model of PLC
7	Input Connector / Terminal Block	Input wiring connection	
8	Output Connector / Terminal Block	Output wiring connection	
9	RS 485 Connector	Built-in RS-485 terminal connection	
10	RS-232C Connector *2	Built-in RS232C TxD, RxD, GND terminal connection	
11	Power Connector*3	Power supply connection	DC24V Power Supply

\*1) In the remote mode, set the mode switch STOP.

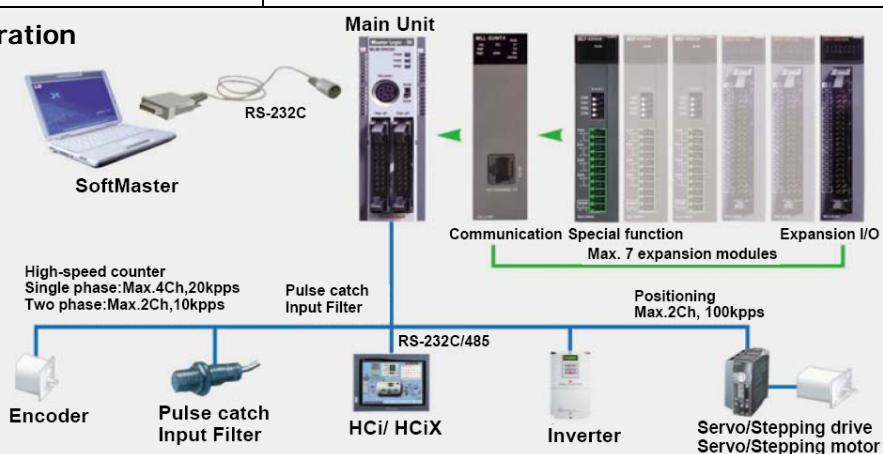
\*2) GND terminal of RS-232C can be used as GND terminal of RS-485.

\*3) Select DC power supply considering current consumption of PLC system.

## Specifications

Model	MLM-DR16S	MLM-DN16S	MLM-DN32S
<b>Performance</b>			
Internal Current Consumption	400mA	280mA	300mA
Control Method	Repetitive, cyclic, interrupt, constant scan		
I/O Control Mode	Refresh mode (Batch processing by scan synchronization) Direct mode by instructions		
Programming Language	Ladder diagram, Instruction List		
Number of Instructions	Basic : 28, Applied : 677		
Processing Speed	0.16 µs/Step (for basic instruction)		
Program Capacity	10 kilo-steps		
Max. I/O Points	480 points (Main + 7 expansions)		
Data Memory	P	P0000 – P127F (2,048 points)	
	M	M0000 – M255F (4,096 points)	
	K	K00000 – K2559F (Special area: K2600 – 2559F) (40,960 points)	
	L	L00000 – L1279F (20,480 points)	
	F	F000 – F255F (4,096 points)	
	T	100msec, 10msec, 1msec: T000 – T255 (Changeable by parameter setting)	
	C	C000 – C255	
	S	S00.00 – S127.99	
	D	D0000 – D5119 (5,120 word)	
	U	U00.00 – U07.31 (Analog data refresh area: 256 word)	
	Z	Z000 – Z127 (128 word)	
No. of Program	N	N0000 – N3935 (3,936 word)	
	128		
	Operation Mode	RUN, STOP, DEBUG	
	Self Diagnostic	Operation delay monitoring, Memory error, I/O error, Power supply failure, etc.	
	Program Port	RS-232C (Loader) Remote connection using RS-232C, RS-485	
	Data Retention at Power Failure	Latch range setting at Basic parameter	
	Built-in Functions	RS-232C/485, High-speed counter, PID control, Pulse catch, Input Filter	
		-	External interrupt, Positioning
	Weight	100g(0.22lb)	

## System Configuration



## Specifications

### DC INPUT

Model		Main Unit					
		MLM-DR16S	MLM-DN16S	MLM-DN32S			
Input Points	8	8	16				
Insulation Method	Photo-coupler insulation						
Rated Input Voltage / Current	DC24V / 4mA (Contact 00 ~ 03 : 7mA)						
Operation Voltage Range	DC 20.4 to 28.8 V (Ripple rate < 5%)						
ON Voltage / Current	DC19V or more / 3mA or more						
OFF Voltage / Current	DC6V or less / 1mA or less						
Input Resistance	5.6 KΩ (Contact 00~03: 3.3 KΩ)						
Response Time	OFF→ON ON→OFF	1 / 3 / 5 / 10 / 20 / 70 / 100 msec (setting by CPU parameter). Initial value: 3msec					
Insulation Pressure	AC 560Vrms / 3 Cycle (altitude 2000m(6,561.68 fts))						
Insulation Resistance	10 MΩ or more by megger						
COMMON Method	8 points / COM		16 points/COM				
Proper Cable Size	Twisted wire 0.3 – 0.75 mm <sup>2</sup> (external diameter ≤ 2.8mm, 0.11inch)						
Operation Indication	Input On, LED On						
Internal Current Consumption	400 mA	240 mA	300 mA				
External Connection Method	9-Pin Terminal block	20-pin Connector	20-pin Connector				

### Open collector OUTPUT

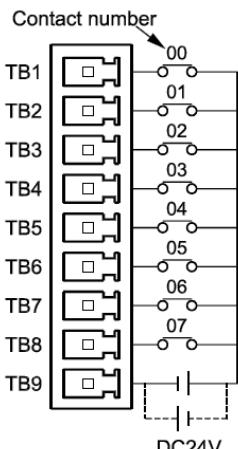
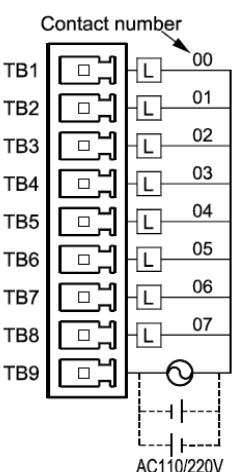
Model		Main Unit	
		MLM-DN16S	MLM-DN32S
Output Points	8	16	
Insulation Method	Photo-coupler insulation		
Rated Load Voltage	DC 12 / 24V		
Load Voltage Range	DC10.2 to 26.4V		
Max. Load Current	0.2A / Point	0.2A/Point,2A/COM	
OFF Leakage Current	0.1mA or less		
Max. Voltage Drop(ON)	DC 0.4V		
Surge Absorber	Zener Diode		
Response Time	OFF→ON ON→OFF	1msec or less 1msec or less(Rated Load, Resistive Load)	
Common Method	8 Points / COM	16 Points / COM	
Internal Current Consumption	180mA	200mA	
External Power Supply	Voltage Current	DC12/24V ± 10% (Ripple Voltage ≤ 4 Vp-p) 24mA or less (at DC24V)	
Operation Indicator	Output ON, LED ON		
External Connection Method	20-pin connector		

## Specifications

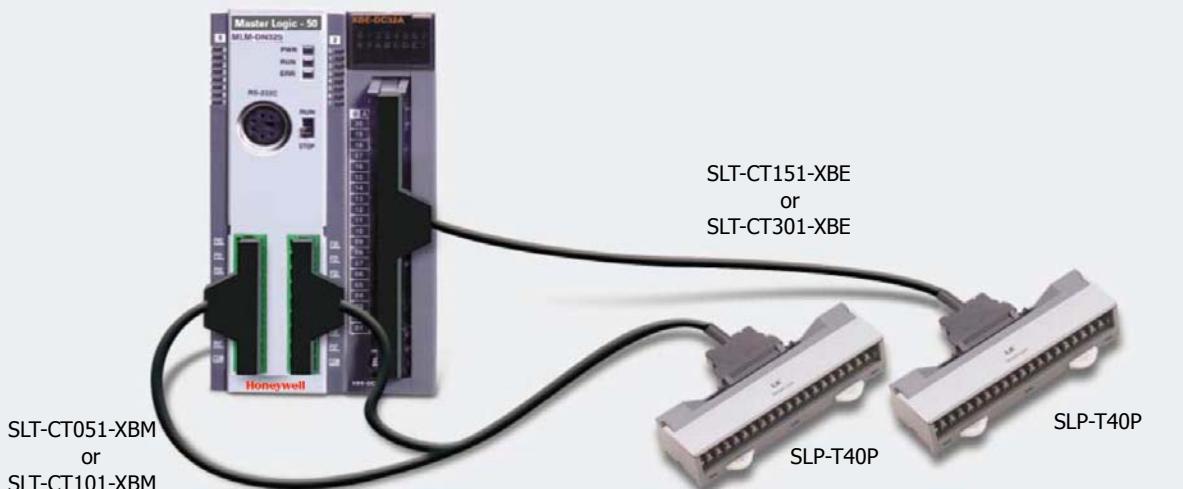
### Relay OUTPUT

Model	Main Unit	
	MLM-DR16S	
Output Points	8 points	
Insulation Method	Relay insulation	
Rated Load Voltage/Current	DC 24V, 2A (Resistive load) / AC220V, 2A ( $\text{COS}\psi = 1$ ), 5A/COM	
Minimum Load Voltage/Current	DC 5V / 1mA	
Maximum Load Voltage/Current	AC250V / DC125V	
OFF Leakage Current	0.1mA (AC250V, 60Hz)	
Max. ON/OFF Frequency	3,600 times / Hour	
Surge Absorber	None	
Service Life	Mechanical	20 million times or more
	Electrical	Rated load voltage/current 100,000 times or more
		AC200V/1.5A, AC240V/1A ( $\text{COS}\psi = 0.7$ ) 100,000 times or more
		AC200V/1A, AC240V/0.5A ( $\text{COS}\psi = 0.35$ ) 100,000 times or more
		DC24V/1A, DC100V/0.1A ( $L / R = 7\text{ms}$ ) 100,000 times or more
Response Time	OFF→ON	10msec or less
	ON→OFF	12msec or less
Common Method	8 points / 1 COM	
Internal Current Consumption	360mA	
Operation Indicator	Output ON, LED ON	
External Connection	9-pin terminal block	

### Input & Output wiring

8-point DC Input	8-point Relay Output
MLM-DR16S	MLM-DR16S
 <p>Contact number TB1 00 TB1 01 TB2 00 TB2 01 TB3 00 TB3 01 TB4 00 TB4 01 TB5 00 TB5 01 TB6 00 TB6 01 TB7 00 TB7 01 TB8 00 TB8 01 TB9 00 TB9 01 DC24V</p>	 <p>Contact number TB1 L 00 TB1 01 TB2 L 01 TB2 02 TB3 L 02 TB3 03 TB4 L 03 TB4 04 TB5 L 04 TB5 05 TB6 L 05 TB6 06 TB7 L 06 TB7 07 TB8 L 07 TB8 08 TB9 L 08 AC110/220V DC24V</p>

## Wiring with Smart Link



ML50 Module	Smart Link Terminal	Description	Cable number	Cable Specification
Main Unit (20+20 pin)	SLP-T40P	Main I/O wiring	SLT-CT101-XBM	Soft tube type 1meter(39.4inch)
			SLT-CT051-XBM	Soft tube type 0.5meter(19.7inch)
Expansion Input and Output(40pin)	SLP-T40P	32 point expansion I/O wiring	SLT-CT151-XBE	Soft tube type 1.5meter(59.1inch)
			SLT-CT301-XBE	Soft tube type 3meter(118.1inch)

## Terminal Layout

20+20pin Terminal Layout(Input)

		PLC		Smart Link	
		Pin number	MLM-DN16S	MLM-DN32S	SLP-T40P
B10	A10	B10	00	00	A1
B09	A09	B09	01	01	B1
B08	A08	B08	02	02	A2
B07	A07	B07	03	03	B2
B06	A06	B06	04	04	A3
B05	A05	B05	05	05	B3
B04	A04	B04	06	06	A4
B03	A03	B03	07	07	B4
B02	A02	B02	COM0	COM0	A5
B01	A01	B01	COM0	COM0	B5
		A10	NC	08	A6
		A09	NC	09	B6
		A08	NC	0A	A7
		A07	NC	0B	B7
		A06	NC	0C	A8
		A05	NC	0D	B8
		A04	NC	0E	A9
		A03	NC	0F	B9
		A02	NC	COM1	A10
		A01	NC	COM1	B10

20+20pin Terminal Layout(Output)

		PLC			Smart Link	
		Pin number	MLM-DN16S	MLM-DN32S	SLP-T40P	
B10	A10	B10	20	20	A11	
B09	A09	B09	21	21	B11	
B08	A08	B08	22	22	A12	
B07	A07	B07	23	23	B12	
B06	A06	B06	24	24	A13	
B05	A05	B05	25	25	B13	
B04	A04	B04	26	26	A14	
B03	A03	B03	27	27	B14	
B02	A02	B02	+12 / 24V	+12 / 24V	A15	
B01	A01	B01	+12 / 24V	+12 / 24V	B15	
		A10	NC	28	A16	
		A09	NC	29	B16	
		A08	NC	2A	A17	
		A07	NC	2B	B17	
		A06	NC	2C	A18	
		A05	NC	2D	B18	
		A04	NC	2E	A19	
		A03	NC	2F	B19	
		A02	COM0	COM0	A20	
		A01	COM0	COM0	B20	

40+40pin Terminal Layout(Output)

		PLC			Smart Link	
		Pin number	MLE-DC32A <sup>(Note1)</sup>	MLE-TN32A <sup>(Note1)</sup>	SLP-T40P (I/O Link terminal)	
B20	A20	B20	00(20)	10(30)	00(20)	A1
B19	A19	B19	01(21)	11(31)	01(21)	B1
B18	A18	B18	02(22)	12(32)	02(22)	A2
B17	A17	B17	03(23)	13(33)	03(23)	B2
B16	A16	B16	04(24)	14(34)	04(24)	A3
B15	A15	B15	05(25)	15(35)	05(25)	B3
B14	A14	B14	06(26)	16(36)	06(26)	A4
B13	A13	B13	07(27)	17(37)	07(27)	B4
B12	A12	B12	08(28)	18(38)	08(28)	A5
B11	A11	B11	09(29)	19(39)	09(29)	B5
B10	A10	B10	0A(2A)	1A(3A)	0A(2A)	A6
B09	A09	B09	0B(2B)	1B(3B)	0B(2B)	B6
B08	A08	B08	0C(2C)	1C(3C)	0C(2C)	A7
B07	A07	B07	0D(2D)	1D(3D)	0D(2D)	B7
B06	A06	B06	0E(2E)	1E(3E)	0E(2E)	A8
B05	A05	B05	0F(2F)	1F(3F)	0F(2F)	B8
B04	A04	B04	NC	NC	NC	A9
B03	A03	B03	NC	NC	NC	B9
B02	A02	B02	COM	COM	DC12/24V	A10
B01	A01	B01			COM	B10
						A20
						B20

\*NOTE1) The number inside () is the address of 64point I/O module.

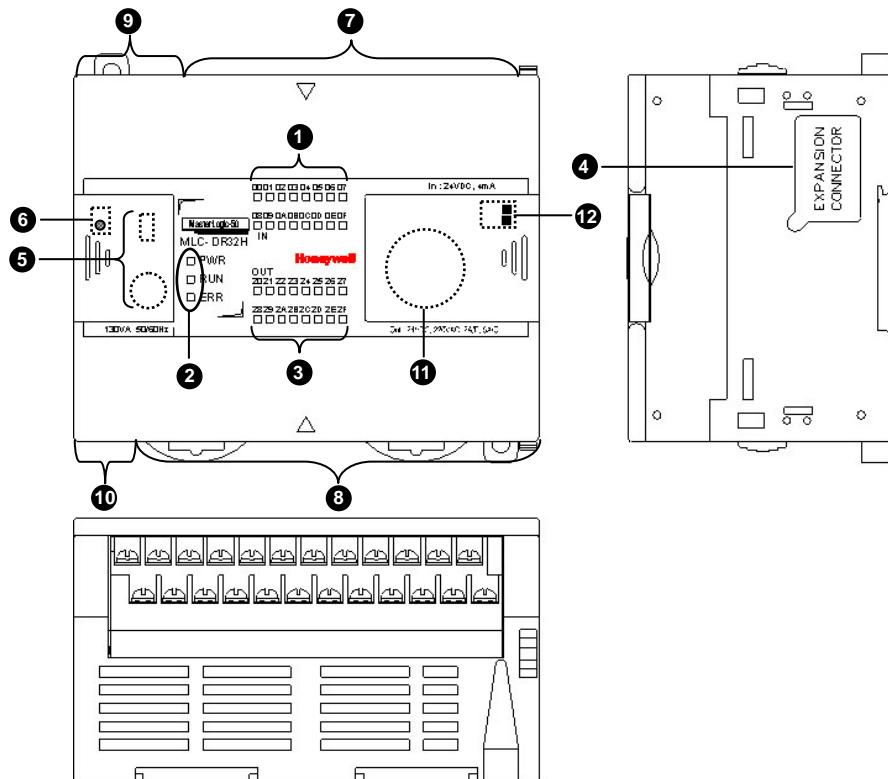
Wiring Diagram																																									
Model	Wiring Diagram																																								
MLM-DN16S Wiring Diagram	<p>Contact → 00 01 02 03 04 05 06 07      08 09 0A 0B 0C 0D 0E 0F</p> <p>DC24V      DC12/24V</p> <table border="1"> <tr><td>B1</td><td>B2</td><td>B3</td><td>B4</td><td>B5</td><td>B6</td><td>B7</td><td>B8</td><td>B9</td><td>B10</td><td>B11</td><td>B12</td><td>B13</td><td>B14</td><td>B15</td><td>B16</td><td>B17</td><td>B18</td><td>B19</td><td>B20</td></tr> <tr><td>A1</td><td>A2</td><td>A3</td><td>A4</td><td>A5</td><td>A6</td><td>A7</td><td>A8</td><td>A9</td><td>A10</td><td>A11</td><td>A12</td><td>A13</td><td>A14</td><td>A15</td><td>A16</td><td>A17</td><td>A18</td><td>A19</td><td>A20</td></tr> </table>	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	B15	B16	B17	B18	B19	B20	A1	A2	A3	A4	A5	A6	A7	A8	A9	A10	A11	A12	A13	A14	A15	A16	A17	A18	A19	A20
B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	B15	B16	B17	B18	B19	B20																						
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A1	A2	A3	A4	A5	A6	A7	A8	A9	A10	A11	A12	A13	A14	A15	A16	A17	A18	A19	A20																						
MLE-DC32A Input Wiring Diagram	<p>Contact → 00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F</p> <p>DC24V</p> <table border="1"> <tr><td>B1</td><td>B2</td><td>B3</td><td>B4</td><td>B5</td><td>B6</td><td>B7</td><td>B8</td><td>B9</td><td>B10</td><td>B11</td><td>B12</td><td>B13</td><td>B14</td><td>B15</td><td>B16</td><td>B17</td><td>B18</td><td>B19</td><td>B20</td></tr> <tr><td>A1</td><td>A2</td><td>A3</td><td>A4</td><td>A5</td><td>A6</td><td>A7</td><td>A8</td><td>A9</td><td>A10</td><td>A11</td><td>A12</td><td>A13</td><td>A14</td><td>A15</td><td>A16</td><td>A17</td><td>A18</td><td>A19</td><td>A20</td></tr> </table>	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	B15	B16	B17	B18	B19	B20	A1	A2	A3	A4	A5	A6	A7	A8	A9	A10	A11	A12	A13	A14	A15	A16	A17	A18	A19	A20
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MLE-TN32A Output Wiring Diagram (SLP-40P)	<p>Contact → 00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F</p> <p>DC12/24V</p> <table border="1"> <tr><td>B1</td><td>B2</td><td>B3</td><td>B4</td><td>B5</td><td>B6</td><td>B7</td><td>B8</td><td>B9</td><td>B10</td><td>B11</td><td>B12</td><td>B13</td><td>B14</td><td>B15</td><td>B16</td><td>B17</td><td>B18</td><td>B19</td><td>B20</td></tr> <tr><td>A1</td><td>A2</td><td>A3</td><td>A4</td><td>A5</td><td>A6</td><td>A7</td><td>A8</td><td>A9</td><td>A10</td><td>A11</td><td>A12</td><td>A13</td><td>A14</td><td>A15</td><td>A16</td><td>A17</td><td>A18</td><td>A19</td><td>A20</td></tr> </table>	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	B15	B16	B17	B18	B19	B20	A1	A2	A3	A4	A5	A6	A7	A8	A9	A10	A11	A12	A13	A14	A15	A16	A17	A18	A19	A20
B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	B15	B16	B17	B18	B19	B20																						
A1	A2	A3	A4	A5	A6	A7	A8	A9	A10	A11	A12	A13	A14	A15	A16	A17	A18	A19	A20																						

## Specifications (MLC-DR32H, MLC-DN32H, MLC-DR64H, MLC-DN64H)

### General

Rated Power Supply Voltage	100 ~ 240V AC						
Inrush Current (when power supply turns on)	50 Apeak or less						
Insulation Resistance	Higher than $10^{M\Omega}$ under DC 500V megger during power terminal and PE terminal						
Withstand Voltage	1500V AC 50/60Hz for 1min across power terminal and PE terminal						
Noise Resistance (IEC61131-2)	Square wave impulse noise : +/-1,500V Electrostatic discharge : 4kV (contact discharge) Rated electromagnetic field noise : 80 to 1,000MHz, 10V/m EFT/B : 2kV in Main unit, 1kV in expansion module						
Operative Limits	Ambient Temperature	0 to 55°C					
	Relative Humidity	5 to 95%RH (non-condensing)					
	Vibration Resistance (IEC61131-2)	Occasional vibration			Continuous vibration		
		Frequency	Acceleration	Pulse width	Frequency	Acceleration	Pulse width
		10 to 57Hz	-	0.075mm	10 to 57Hz	-	0.035mm
		57 to 150Hz	9.8m/s <sup>2</sup>	-	57 to 150Hz	4.9m/s <sup>2</sup>	-
		10 times each direction(X, Y and Z)					
	Shock Resistance (IEC61131-2)	Peak Acceleration: 147 m/s <sup>2</sup> (15g) Duration: 11ms Pulse waveform: Half-sine, 3 times each direction per each axis					
Transportation & Storage	Ambient temperature	-25 to +70 °C					
	Relative Humidity	5 to +95% RH (non-condensing)					
Pollution Level	$\leq 2$  Pollution level indicates the degree to which conductive material is generated in the environment where the equipment is used. Pollution level 2 is the condition that only non-conductive pollution occurred but temporary conductivity may be produced due to condensing.						
Operating Ambience	Free from corrosive gases and excessive dust						
Altitude	Up to 2,000 meters(6,561.68 feet)						
Cooling	Air-cooling						
Base Module (unit: $\frac{mm}{inch}$ )	$\frac{114.0}{4.488} (W) \times \frac{90.0}{3.543} (H) \times \frac{64.0}{2.520} (D)$			MLC-DN32H, MLC-DR32H			
	$\frac{180.0}{7.087} (W) \times \frac{90.0}{3.543} (H) \times \frac{64.0}{2.520} (D)$			MLC-DN64H, MLC-DR64H			
Expansion Module (unit: $\frac{mm}{inch}$ )	$\frac{30.0}{1.181} (W) \times \frac{90.0}{3.543} (H) \times \frac{60.0}{2.362} (D)$			MLM-DN16S, MLM-DN32S MLM-DR16S			
	$\frac{20.0}{0.787} (W) \times \frac{90.0}{3.543} (H) \times \frac{60.0}{2.362} (D)$			MLE-DC __ A, MLE-TN __ A MLF- __ 04A			
	$\frac{27.0}{1.063} (W) \times \frac{90.0}{3.543} (H) \times \frac{60.0}{2.362} (D)$			MLE-RY16A			

## Indicators and Connectors



Name	Description		
1	Input LED	Input Indication	Red on/off. Input signal on/off
2	Condition LED	PWR: Power indication	Red on/off. Power on/off
		RUN : RUN indication	Green on/off. PLC RUN/STOP
		ERR : Error indication	Red on and off. PLC error. Red off. PLC normal condition
		Output LED	On/off. Output signal on/off.
4	Expansion Module Connector	Connection of expansion module (I/O, Special function, Communication)	
5	PADT connector	PADT connection	Connector for SoftMaster / SoftMaster-NM connection USB (USB 1.1 supported) 1 Ch., RS-232C 1 Ch.
6	Model Switch *1	Model setting	Setting RUN/STOP model of PLC
7	Input Terminal Block	Input wiring connection	
8	Output Terminal Block	Output wiring connection	
9	Built-in Communication Terminal Block	Built-in RS-485 terminal connection	
		Built-in RS232C TxD, RxD, SG terminal connection	
10	Power Terminal Block*3	Power supply connection	AC 100 ~ 240 V
11	Battery Holder	Battery (3V) holder for data back-up	
12	O/S Mode Dip Switch	Dip Switch for setting operation or O/S download mode	

\*1) In the remote mode, set the mode switch STOP.

\*2) SG terminal of RS-232C can be used as SG terminal of RS-485.

Specifications									
Model	MLC-DR32H	MLC-DN32H	MLC-DR64H	MLC-DN64H					
Performance									
Internal Current Consumption	660mA	260mA	1040mA	330mA					
Control Method	Repetitive, cyclic, interrupt, constant scan								
I/O Control Mode	Refresh mode (Batch processing by scan synchronization) Direct mode by instructions								
Programming Language	Ladder diagram, Instruction List								
Number of Instructions	Basic : 28, Applied : 687								
Processing Speed	83 ns/Step (for basic instruction)								
Program Capacity	15 kilo-steps								
Max. I/O Points	672 points(Main + 10 expansions)		704 points (Main + 10 expansions)						
Data Memory	P	P0000 ~ P1023F (16,384 points)							
	M	M0000 ~ M1023F (16,384 points)							
	K	K00000 ~ K4095F (Special area: K2600~3339F) (65,536 points)							
	L	L00000 ~ L2047F (32,768 points)							
	F	F000 ~ F1023F (16,384 points)							
	T	100ms, 10ms, 1ms: T000 ~ T1023 (Changeable by Parameter setting)							
	C	C000 ~ C1023							
	S	S00.00 ~ S127.99							
	D	D0000 ~ D10,239 (10,240 word)							
	U	U00.00 ~ U0A.31 (Analog data refresh area: 352 word)							
	Z	Z000 ~ Z127 (128 word)							
	N	N0000 ~ N5119 (5120 word)							
	R	R0000 ~ R10239							
No. of Program	128								
Operation Mode	RUN, STOP, DEBUG								
Self Diagnostic	Operation delay monitoring, memory error, I/O error, battery error, power error, etc.								
Program Port	USB (Rev 1.1), RS-232C (6 pin)								
Data Retention at Power Failure	Latch range setting at Basic parameter								
Built-in Functions	RS-232C/485, High-speed counter, PID control, Pulse catch, Input Filter, External interrupt, Positioning								
Weight	600g (1.32lb)	500g (1.10lb)	900g (1.98lb)	800g (1.76lb)					
System Configuration									
<p>High Speed Counter Single Phase : 100kpps 4ch, 20kpps 4ch Two Phase : 50kpps 2ch, 10kpps 2ch</p> <p>Communication Special function Max. 10 Expansion Modules</p> <p>Positioning Max. 2ch, 100kpps</p>									

Specifications				
DC INPUT				
Model		Main Unit		
		MLC-DR32H	MLC-DN32H	MLC-DR64H
Input Points		16		32
Insulation Method		Photo-coupler insulation		
Rated Input Voltage / Current		DC24V / 4mA (Contact 00 ~ 07 : 9mA)		
Operation Voltage Range		DC 20.4 to 28.8 V (Ripple rate < 5%)		
ON Voltage / Current		DC19V or more / 3mA or more		
OFF Voltage / Current		DC6V or less / 1mA or less		
Input Resistance		5.6 KΩ (P00~P07: 2.7 KΩ)		
Response Time	OFF→ON	1 / 3 / 5 / 10 / 20 / 70 / 100 msec (setting by CPU parameter). Initial value: 3msec		
	ON→OFF			
Insulation Pressure		AC 560Vrms / 3 Cycle (altitude 2000m(6,561.68 ft))		
Insulation Resistance		10 MΩ or more by megger		
COMMON Method		16 points / COM		
Proper Cable Size		Twisted wire 0.3 – 0.75 mm <sup>2</sup> (external diameter ≤ 2.8mm, 0.11inch)		
Operation Indication		Input On, LED On		
Internal Current Consumption		200mA (when all point On)		
External Connection Method		24 points connecting connector (M3 X 6 screw)		42 point connecting connector (M3 X 6 screw)
Open collector OUTPUT				
Model		Main Unit		
		MLC-DN32H		MLC-DN64H
Output Points		16		32
Insulation Method		Photo-coupler insulation		
Rated Load Voltage		DC 12 / 24V		
Load Voltage Range		DC10.2 to 26.4V		
Max. Load Current		0.5A / 1point (P20~23:0.1A/point)		
OFF Leakage Current		0.1mA or less		
Max. Inrush Current		4A / 10msec or less		
Max. Voltage Drop(ON)		DC 0.4V or less		
Surge Absorber		Zener Diode		
Response Time	OFF→ON	1msec or less		
	ON→OFF	1msec or less(Rated Load, Resistive Load)		
Common Method		4 Points / COM		4 Points / COM (COM0~COM3) 8 Points / COM (COM4~COM5)
Internal Current Consumption		400mA		500mA
External Power Supply	Voltage	DC12/24V ± 10% (Ripple Voltage ≤ 4 Vp-p)		
	Current	25mA or less (at DC24V)		
Operation Indicator		Output ON, LED ON		
External Connection Method		24 points connecting connector (M3 X 6 screw)		42 point connecting connector (M3 X 6 screw)

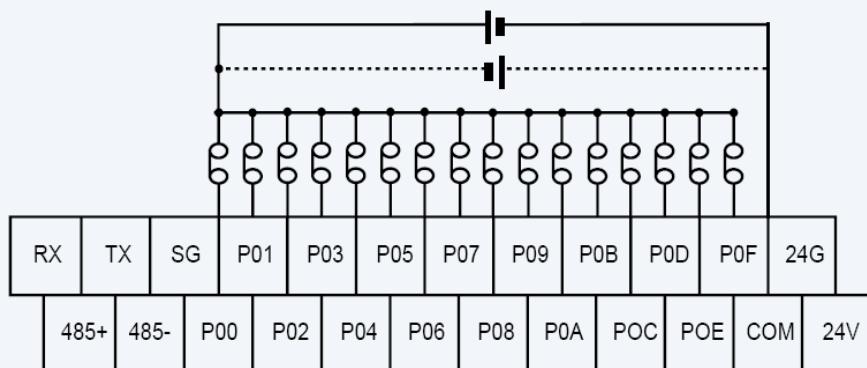
## Specifications

### Relay OUTPUT

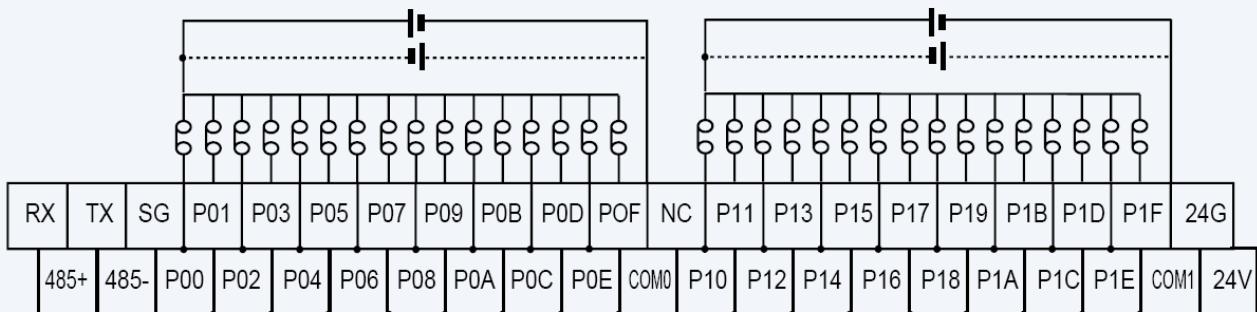
Model	Main Unit	
	MLC-DR32H	MLC-DR64H
Output Points	16	32
Insulation Method	Relay insulation	
Rated Load Voltage/Current	DC 24V, 2A (Resistive load) / AC220V, 2A ( $\text{COS}\psi = 1$ ), 5A/COM	
Minimum Load Voltage/Current	DC 5V / 1mA	
Maximum Load Voltage/Current	AC250V / DC125V	
OFF Leakage Current	0.1mA (AC220V, 60Hz)	
Max. ON/OFF Frequency	3,600 times / Hour	
Surge Absorber	None	
Service Life	Mechanical	20 million times or more
	Electrical	Rated load voltage/current 100,000 times or more
		AC200V/1.5A, AC240V/1A ( $\text{COS}\psi = 0.7$ ) 100,000 times or more
		AC200V/1A, AC240V/0.5A ( $\text{COS}\psi = 0.35$ ) 100,000 times or more
		DC24V/1A, DC100V/0.1A ( $L / R = 7\text{ms}$ ) 100,000 times or more
Response Time	OFF→ON	10msec or less
	ON→OFF	12msec or less
Common Method	4 points / COM	4 point / COM (COM0~COM3) 8 point / COM (COM4~COM5)
Internal Current Consumption	360mA (When all output are On)	720mA (When all output are On)
Operation Indicator	Output ON, LED ON	
External Connection Method	24 point connecting connector (M3 X 6 screw)	42 point connecting connector (M3 X 6 screw)

### Input & Output wiring

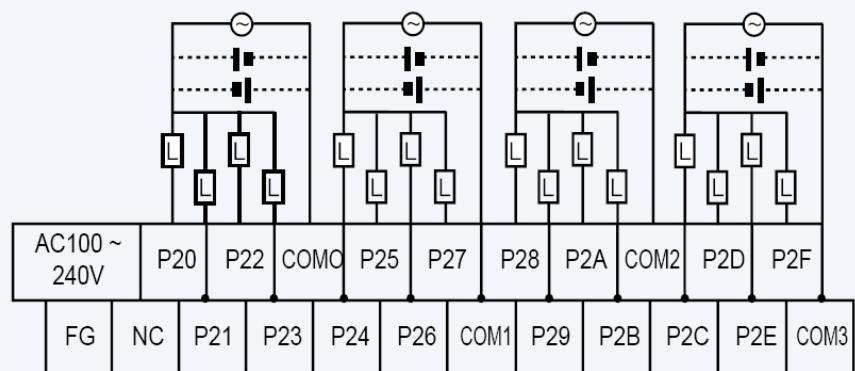
Input wiring (MLC-DR32H / MLC-DN32H)



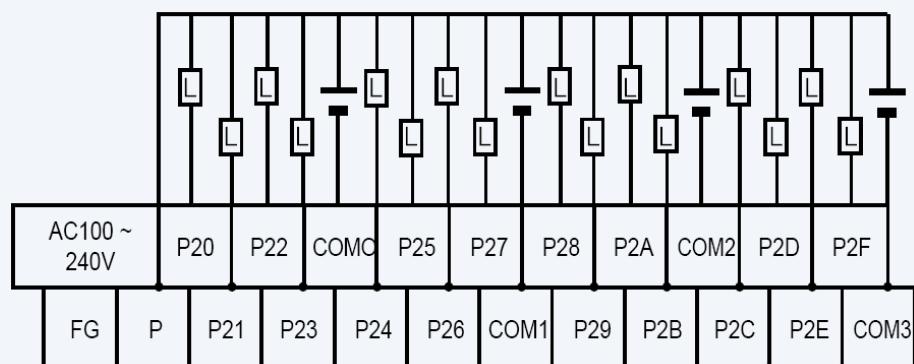
Input wiring (MLC-DR64H / MLC-DN32H)



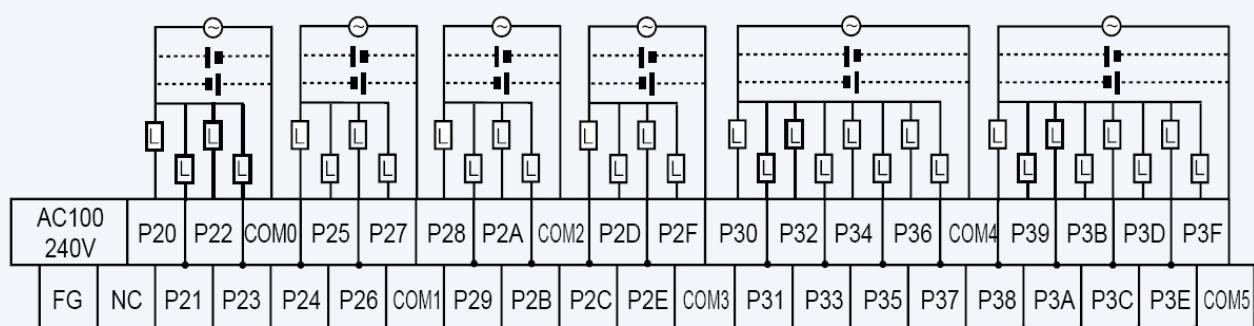
Relay Output wiring (MLC-DR32H)



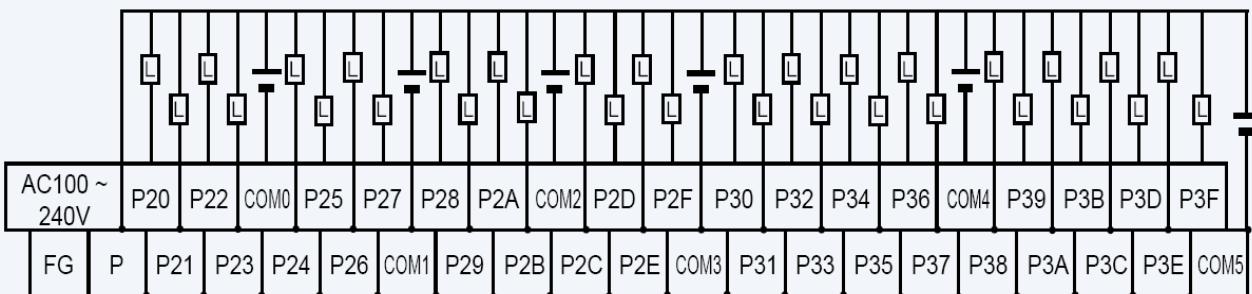
Open Collector wiring (MLC-DN32H)



Relay Output wiring (MLC-DR64H)



## Relay Output wiring (MLC-DN64H)



## Specifications

### High Speed Counter

Model	CPU type	
	S type (MLM)	H type (MLC)

### Function

Pulse Input Mode	Incremental / Decremental counter by program when input is 1-phase pulse.
	Incremental / Decremental counter by B-axis input when input is 1-phase pulse.
	Incremental / Decremental counter (4 multiplication) by phase difference when input 2-phase pulse.
	Incremental counter by CW/CCW input
Counter Mode	Linear counter (If 32 bit range exceeded, Carry/Borrow occurs)
	Ring counter: Counter rotating between value in 0 ~ (Ring counter setting value -1)
Present Value Preset	Changes present value of counter to optional value – Internal preset / External preset
Comparison Output	Sets output contact when counter value corresponds with comparison output condition. Comparison output condition : >, ≥, =, ≤, <, inclusion, exclusion
No. of Rotation	Outputs the rotation number of input pulse per unit time.

### Performance

No. of Points	1-phase 4 points, 2-phase 2 points	1-phase 8 points, 2-phase 4 points
Input Points	A Phase, B Phase, Preset input	
Counting Range	Linear counter: - 2,147,483,648 ~ 2,147,483,647 (Binary 32 Bit)	
Counting Speed	1-phase 20kpps 4ch 2-phase 10kpps 2ch	1-phase 100kpps 4ch, 20kpps 4ch 2-phase 50kpps 2ch, 10kpps 2ch
Incremental Functions	Ring counter, preset, Rotation number per unit time, Comparison output, Latch counter	

### Electrical

Input Voltage	DC 24V (20.4V ~ 28.8V)
Input Current	7mA
On Guaranteed Voltage (Minimum)	DC 20.4 V
Off Guaranteed Voltage (Maximum)	DC 6V

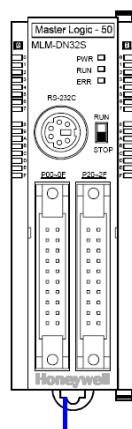
## High-speed Counter Terminal

High speed counter accurately counts the number of high speed pulse generated from encoder or pulse generator.

Terminal Number	1-Phase		2-Phase	
	Signal name	Description	Signal name	Description
P000	Ch0 counter input	Counter input	Ch0 A-axis input	A-axis input
P001	Ch1 counter input	Counter input	Ch0 B-axis input	B-axis input
P002	Ch2 counter input	Counter input	Ch2 A-axis input	A-axis input
P003	Ch3 counter input	Counter input	Ch2 B-axis input	B-axis input
P004	Ch0 preset 24V	Preset input	Ch0 preset 24V	Preset input
P005	Ch1 preset 24V	Preset input	-	-
P006	Ch2 preset 24V	Preset input	Ch2 preset 24V	Preset input
P007	Ch3 preset 24V	Preset input	-	-
COM0	Input COMMON	COMMON	Input COMMON	COMMON

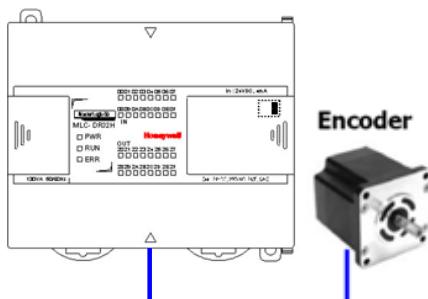
Terminal Number	1-Phase		2-Phase	
	Signal name	Description	Signal name	Description
P000	Ch0 counter input	Counter input	Ch0 A-axis input	A-axis input
P001	Ch1 counter input	Counter input	Ch0 B-axis input	B-axis input
P002	Ch2 counter input	Counter input	Ch2 A-axis input	A-axis input
P003	Ch3 counter input	Counter input	Ch2 B-axis input	B-axis input
P004	Ch4 counter input	Counter input	Ch4 A-axis input	A-axis input
P005	Ch5 counter input	Counter input	Ch4 B-axis input	B-axis input
P006	Ch6 counter input	Counter input	Ch6 A-axis input	A-axis input
P007	Ch7 counter input	Counter input	Ch6 B-axis input	B-axis input
P008	Ch0 preset 24V	Preset input	Ch0 preset 24V	Preset input
P009	Ch1 preset 24V	Preset input	-	-
P00A	Ch2 preset 24V	Preset input	Ch2 preset 24V	Preset input
P00B	Ch3 preset 24V	Preset input	-	-
P00C	Ch4 preset 24V	Preset input	Ch4 preset 24V	Preset input
P00D	Ch5 preset 24V	Preset input	-	-
P00E	Ch6 preset 24V	Preset input	Ch6 preset 24V	Preset input
P00F	Ch7 preset 24V	Preset input	-	-
COM0	Input COMMON	COMMON	Input COMMON	COMMON



High speed Counter

One phase : Max. 4Ch, 20kpps

Two phase : Max. 2Ch, 10kpps

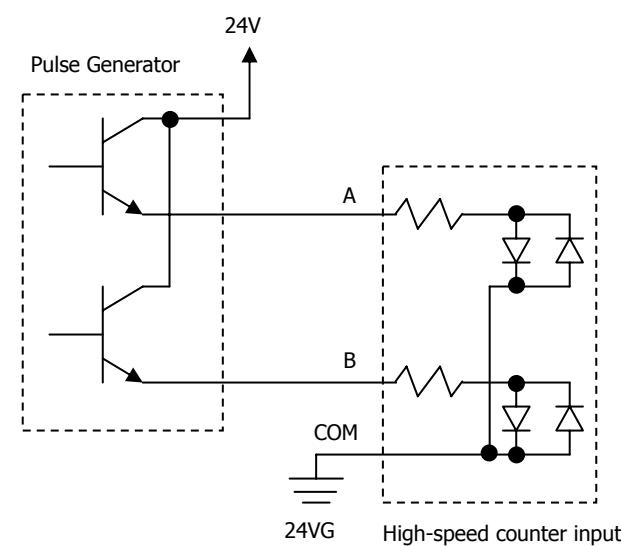


High-speed counter

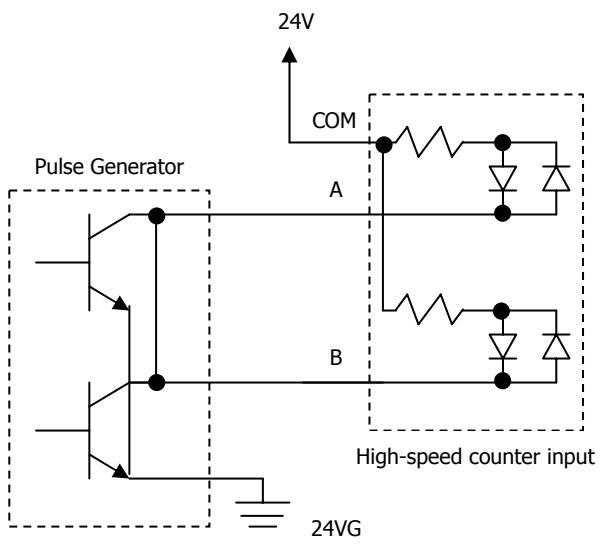
One phase: 100kpps 4ch, 20kpps 4ch

Two phase: 50kpps 2ch, 10kpps 2ch

## Encoder Wiring



Voltage Output Encoder



Open Collector Encoder

## Operation Setting Address of High-speed Counter ("S" type)

ITEM	Device Range for each Channel				Remark
	CH1	CH2	CH3	CH4	
Counter Enable	K2600	K2700	K2800	K2900	Bit
Counter Internal Preset Assignment	K2601	K2701	K2801	K2901	Bit
Counter External Preset Enable	K2602	K2702	K2802	K2902	Bit
Subtraction Counter Assignment	K2603	K2703	K2803	K2903	Bit
Comparison Output Enable	K2604	K2704	K2804	K2904	Bit
Rotation Number per Unit Time Enable	K2605	K2705	K2805	K2905	Bit
Latch Counter Enable	K2606	K2706	K2806	K2906	Bit
Carry Signal(Bit)	K2610	K2710	K2810	K2910	Bit
Borrow Signal(Bit)	K2611	K2711	K2811	K2911	Bit
Comparison Output Signal	K2612	K2712	K2812	K2912	Bit

## Operation Setting Address of High-speed Counter ("H" type)

ITEM	Device Range for each Channel								Remark
	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8	
Counter Enable	K2600	K2700	K2800	K2900	K21800	K21900	K22000	K22100	Bit
Counter Internal Preset Assignment	K2601	K2701	K2801	K2901	K21801	K21901	K22001	K22101	Bit
Counter External Preset Enable	K2602	K2702	K2802	K2902	K21802	K21902	K22002	K22102	Bit
Subtraction Counter Assignment	K2603	K2703	K2803	K2903	K21803	K21903	K22003	K22103	Bit
Comparison Output Enable	K2604	K2704	K2804	K2904	K21804	K21904	K22004	K22104	Bit
Rotation Number per Unit Time Enable	K2605	K2705	K2805	K2905	K21805	K21905	K22005	K22105	Bit
Latch Counter Enable	K2606	K2706	K2806	K2906	K21806	K21906	K22006	K22100	Bit
Carry Signal(Bit)	K2610	K2710	K2810	K29100	K21810	K21910	K22010	K22110	Bit
Borrow Signal(Bit)	K2611	K2711	K2811	K29101	K21811	K21911	K22012	K22111	Bit
Comparison Output 0 Signal	K2612	K2712	K2812	K29102	K21812	K21912	K22013	K22112	Bit
Comparison Output 1 Signal	K2613	K2713	K2813	K29103	K21813	K21913	K22013	K22113	Bit

Parameter Setting Address of High-speed Counter ("S" type)							
ITEM	Description		Device Range for each Channel				Remark
	Setting Value	Setting Description	CH1	CH2	CH3	CH4	
Counter Enable	H0000 H0001	Linear Counter Setting Ring Counter Setting	K300	K330	K360	K390	Word
Pulse Input Mode Setting	H0000 H0001 H0002 H0003	1phase 1input 1multiplication 1phase 2input 1multiplication CW/CCW 2phase 4multiplication	K301	K331	K361	K391	Word
Comparison Output Mode Setting	H0000 H0001 H0002 H0003 H0004 H0005 H0006	(Single comparison) < (Single comparison) ≤ (Single comparison) = (Single comparison) ≥ (Single comparison) > (Section comparison) Inclusion (Section comparison) Exclusion	K302	K332	K362	K392	Word
Internal Preset Value Setting	-2,147,483,648~2,147,483,647		K304	K334	K364	K394	Word
External Preset Value Setting	-2,147,483,648~2,147,483,647		K306	K336	K366	K396	Word
Ring Counter Value Setting	-2,147,483,648~2,147,483,647		K310	K340	K370	K400	Word
Min. Comparison Output Value Setting	-2,147,483,648~2,147,483,647		K312	K342	K372	K402	Word
Max. Comparison Output Value Setting	-2,147,483,648~2,147,483,647		K314	K344	K374	K404	Word
Comparison Output Contact Assignment	0x0000 0x0001 0x0002 0x0003 0x0004 0x0005 0x0006 0x0007	P20 P21 P22 P23 P24 P25 P26 P27	K320	K350	K380	K410	Word
Rotation Number Setting per Unit Time	0 ~ 60000		K322	K352	K382	K412	Word
Pulse Number Setting per Rotation	0 ~ 60000		K323	K353	K383	K413	Word

Parameter Setting Address of High-speed Counter ("H" type)								
ITEM	Description		Device Range for each Channel				Remark	
	Setting Value	Setting Description	CH1	CH2	CH3	CH4		
Counter Enable	H0000	Linear Counter Setting	K300	K330	K360	K390	Word	
	H0001	Ring Counter Setting	K2220	K2250	K2280	K2310		
Pulse Input Mode Setting	H0000	1phase 1input 1multiplication	K301	K331	K361	K391	Word	
	H0001	1phase 2input 1multiplication	K2221	K2251	K2281	K2311		
Comparison Output 0 Mode Setting	H0000	(Single comparison) <	K302	K332	K362	K392	Word	
	H0001	(Single comparison) ≤						
	H0002	(Single comparison) =						
	H0003	(Single comparison) ≥						
	H0004	(Single comparison) >						
	H0005	(Section comparison) Inclusion						
Comparison Output 1 Mode Setting	H0006	(Section comparison) Exclusion	K2222	K2252	K2282	K2312	Word	
	H0000	(Single comparison) <	K303	K333	K363	K393		
	H0001	(Single comparison) ≤						
	H0002	(Single comparison) =						
	H0003	(Single comparison) ≥						
	H0004	(Single comparison) >						
Internal Preset Value Setting	-2,147,483,648 ~ 2,147,483,647			K304	K334	K364	K394	DWord
				K2224	K2254	K2284	K2314	
External Preset Value Setting	-2,147,483,648 ~ 2,147,483,647			K306	K336	K366	K396	DWord
				K2226	K2256	K2286	K2316	
Min. Ring Counter Value Setting	-2,147,483,648 ~ 2,147,483,645			K308	K338	K368	K398	DWord
				K2228	K2258	K2288	K2318	
Max. Ring Counter Value Setting	-2,147,483,648 ~ 2,147,483,645			K310	K340	K370	K400	DWord
				K2230	K2260	K2290	K2320	
Min. Comparison Output Value Setting	-2,147,483,648 ~ 2,147,483,645			K312	K342	K372	K402	DWord
				K2232	K2262	K2292	K2322	
Max. Comparison Output Value Setting	-2,147,483,648 ~ 2,147,483,645			K314	K344	K374	K404	DWord
				K2234	K2264	K2294	K2324	
Comparison Output 0 Contact Assignment	0xFFFF	No use	K320	K350	K380	K410	Word	
	0x0000	P20						
	0x0001	P21						
	0x0002	P22						
	0x0003	P23						
	0x0004	P24						
	0x0005	P25						
	0x0006	P26						
	0x0007	P27						
	0x0008	P28	K2240	K2270	K2300	K2330		
	0x0009	P29						
	0x000A	P2A						
	0x000B	P2B						
	0x000C	P2C						
	0x000D	P2D						
	0x000E	P2E						
	0x000F	P2F						

Parameter Setting Address of High-speed Counter ("H" type)							
ITEM	Description		Device Range for each Channel				Remark
	Setting Value	Setting Description	CH1	CH2	CH3	CH4	
			CH5	CH6	CH7	CH8	
Comparison Output 1 Contact Assignment	0xFFFF	No use					
	0x0000	P20					
	0x0001	P21	K321	K351	K381	K411	Word
	0x0002	P22					
	0x0003	P23					
	0x0004	P24					
	0x0005	P25					
	0x0006	P26					
	0x0007	P27					
	0x0008	P28					
	0x0009	P29					
	0x000A	P2A	K2241	K2271	K2301	K2331	
	0x000B	P2B					
	0x000C	P2C					
	0x000D	P2D					
	0x000E	P2E					
	0x000F	P2F					

### High Speed Counter Monitoring

#### Special Function Monitoring

Special Function Monitoring in SoftMaster can monitor operation condition and data of high speed counter while PLC is on-line.

#### Device Monitoring

While PLC is on-line, Device Monitoring can monitor the operation condition and data by monitoring the device setting area.

### Parameter Setting Address of High-speed Counter ("S" type)

Item	Device Range for Each Channel				Remark
	CH1	CH2	CH3	CH4	
Present Counter Value	K262	K272	K282	K292	Double Word
No. of Rotation per Unit Time	K264	K274	K284	K294	Double Word
Error Code	K266	K276	K286	K296	Word

### Parameter Setting Address of High-speed Counter ("H" type)

Item	Device Range for Each Channel								Remark
	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8	
Present Counter Value	K262	K272	K282	K292	K2182	K2192	K2202	K2212	Word
No. of Rotation per Unit Time	K264	K274	K284	K294	K2184	K2194	K2204	K2214	Word
Error Code	K266	K276	K286	K296	K2186	K2196	K2206	K2216	Word

Error Code of High-speed Counter	
Error Code(Decimal)	Error Description
20	Out of Counter type range
21	Out of Pulse input type range
22	When Requesting RUN of CH1[3] during 2-phase operation of CH0[2] (Use of CH1[3] is not available during 2-phase operation of CH0[2])
23	Out of Comparison output type range
25	Internal preset value setting error(Out of counter range)
26	External preset value setting error(Out of counter range)
27	Ring counter setting error(Ring counter value should be set as 2 or more)
28	Comparison minimum value setting error(Out of minimum input range)
29	Comparison maximum value setting error(Out of maximum input range)
30	Minimum comparison output1 > Maximum comparison output1
31	Contact assignment value setting error of comparison output
34	Out of unit time setting range
35	Out of pulse value range per rotation

## Specifications

### Positioning Function

#### Performance

No. of Control Axis	2-axis	
Interpolation	2-axis linear interpolation	
Control Mode	Position control, Speed control, Speed / Position switching control, Position / Speed switching control	
Control Unit	Pulse	
Positioning Data	30-step pattern(MLM S type) and 80-step(MLC H type)for each axis (set in SoftMaster) (Operation step number: 1~30, MLC:1~80)	
Positioning Monitor	Dedicated monitoring function for positioning in SoftMaster	
Back-up	Permanent Backup of downloaded parameter (FLASH memory)	
	2-month Super Cap. Backup of parameter / data modified during operation (RAM)	
	Permanent Backup of parameter / data in RAM by instruction (FLASH memory)	
Positioning	Positioning Method	Absolute / Incremental method
	Positioning Range	- 2,147,483,648 ~ 2,147,483,647
	Speed Range	1~ 100,000 (pulse / sec)
	Acceleration / Deceleration Type	Trapezoidal acceleration / deceleration
	Acceleration / Deceleration Time	1~ 10,000 msec ( 4 patterns each can be set)
Maximum Output Pulse	100 kpps	
Maximum Distance of Connections	2 meters (6.56 feet)	

#### Electrical

Output	Signal	Output Pulse			
	Rated Input Voltage	DC 5 ~ 24V			
	Load Voltage Range	DC 4.75 ~ 26.4V			
	Max. Load Current/Inrush Current	100mA (1 point) 1A / 10msec or less			
	Max. Voltage Drop(ON)	DC 0.3V or less			
	Leakage Current(OFF)	0.1mA or less			
	Response Time	100µs or less			
Input	Signal	External High Limit	External Low Limit	Approximate Zero	Zero
	Rated Input Voltage / Current	DC 24V / 7mA		DC 24V / 4mA	
	Load Voltage Range	DC 20.4 ~ 28.8 V			
	ON Voltage / Current	DC 19V / 5.7 mA or more		DC 19V / 3.4 mA or more	
	OFF Voltage / Current	DC 6V / 1.8 mA or less		DC 6V / 1.1 mA or less	
	Input Resistance	3.3 KΩ		5.6 KΩ	
	Response Time	0.5 ms or less			

## Positioning Function Terminals ("S" type)

Item	Pin Number		Signal Name		Direction of Positioning Signal	Operating Direction
	X axis	Y axis				
Output	A1	A2	Pulse	Pulse output (open collector)	→	-
	A3	A4	Direction	Pulse output (open collector)	→	-
	A9/A10		DC24V	External 24V Power supply	→	-
	B9/B10		Output COM	External 24V GND	→	
Input	A1	A3	Limit L	Low Limit	←	Edge
	A2	A4	Limit H	High Limit	←	Edge
	A5	A7	DOG	Near Point	←	Edge
	A6	A8	Zero	Zero signal (+24V)	←	Edge
	A9/10, B9/10		Input COM	COMMON	←	-

## Positioning Function Terminals ("H" type)

Item	Pin Number		Signal Name		Direction of Positioning Signal	Operating condition
	X axis	Y axis				
Output	P0020	P0021	Pulse	Pulse/CW (Open collector)	→	DC5~24V
	P0022	P0023	Direction	Direction/CCCW (Open collector)	→	
	P		DC12V	External power supply	→	
	COMO		Output COM	External 24V GND	→	
Input	P0008	P000A	Limit L	Low limit	←	7.4mA/24V
	P0009	P000B	Limit H	High limit	←	
	P000C	P000E	DOG	Near point	←	
	P000D	P000F	Origin	Zero signal(+24V)	←	
	COM		Input COM	Common	←	

## Storage Range of Positioning Parameter

Assigned Parameters are stored on the following memory range. While operating PLC, command parameters can be changed by changing data in corresponding range.

	Item	Setting Range	Initial Value	Device Range		Remark
				X axis	Y axis	
Basic Parameter	Positioning	0:Disabled,1:Enabled	0	K4870	K5270	Bit
	Pulse Output Level	0:Low active, 1:High active	0	K4871	K5271	Bit
	Pulse Output mode	0:CW/CCW, 1:Pulse/Direction	0	K4873	K5273	Bit
	M Code output mode	0:None, 1:WITH, 2:AFTER	0	K4681 K4682	K5081 K5082	Bit
	Bias Speed	1~100,000 [Pulse/sec]	1	K450	K490	Double Word
	Speed Limit	1~100,000 [Pulse/sec]	100,000	K452	K492	Double Word
	Acceleration Time1	0~10,000 [Unit:msec]	500	K454	K494	Word
	Deceleration Time1	0~10,000 [Unit:msec]	500	K455	K495	Word
	Acceleration Time2	0~10,000 [Unit:msec]	1,000	K456	K496	Word
	Deceleration Time2	0~10,000 [Unit:msec]	1,000	K457	K497	Word

	Item	Setting Range	Initial Value	Device Range		Remark
				X axis	Y axis	
Basic Parameter	Acceleration Time3	0~10,000 [Unit:msec]	1,500	K458	K498	Word
	Deceleration Time3	0~10,000 [Unit:msec]	1,500	K459	K499	Word
	Acceleration Time4	0~10,000 [Unit:msec]	2,000	K460	K500	Word
	Deceleration Time4	0~10,000 [Unit:msec]	2,000	K461	K501	Word
	Soft High Limit	-2,147,483,648~2,147,483,647[pulse]	2,147,483,647	K462	K502	Double Word
	Soft Low Limit	-2,147,483,648~2,147,483,647[pulse]	-2,147,483,648	K464	K504	Double Word
	Backlash Compensation Amount	0~65,535[pulse]	0	K466	K506	Word
	Detection of Soft High/Low Limit during equal speed operation	0:Disabled,1:Enabled	0	K4684	K5084	Bit
	Use of High/Low Limit	0:Disabled,1:Enabled	1	K4872	K5272	Bit
Zero/Manual Parameter	Zero Address	-2,147,483,648~2,147,483,647[pulse]	0	K469	K509	Double Word
	Zero-return High Speed	1~100,000 [Pulse/sec]	5,000	K471	K511	Double Word
	Zero-return Low Speed	1~100,000 [Pulse/sec]	500	K473	K513	Double Word
	Zero-return Acceleration Time	0~10,000 [Unit:msec]	1,000	K475	K515	Word
	Zero-return Deceleration Time	0~10,000 [Unit:msec]	1,000	K476	K516	Word
	Zero-return Dwell Time	0~50,000 [Unit:msec]	0	K477	K517	Word
	Zero-return method	0 : Zero detection after near zero OFF 1: Zero detection after deceleration when near zero is ON 2 : Zero detection by near zero	0	K4780 K4781	K5180 K5181	Word
	Zero-return direction	0:Forward, 1:Reverse	1	K4782	K5182	Bit
	JOG High Speed	1~10,000 [Pulse/sec]	5,000	K479	K519	Double Word
	JOG Low Speed	1~10,000 [Pulse/sec]	1,000	K481	K521	Double Word
	JOG Acceleration time	0~65,535[Unit:msec]	1,000	K483	K523	Word
	JOG Deceleration time	0~65,535[Unit:msec]	1,000	K484	K524	Word
	Inching Speed	0~65,535[Pulse/sec]	100	K485	K525	Word

## Positioning Dedicated Instruction

Instruction <sup>*1)</sup>	Description	Instruction Operand <sup>*1)</sup>
ORG	Zero Return Start	Slot, Instruction axis
FLT	Floating-point zero setting	Slot, Instruction axis
DST	Direct Start	Slot, Instruction axis, Position, Speed, Dwell time,
		M code, Control word
IST	Indirect Start	Slot, Instruction axis, Step number
LIN	Linear Interpolation Start	Slot, Instruction axis, Step number, Axis information
SST	Simultaneous Start	Slot, Instruction axis, X-axis step number Y-axis step number, Z-axis step number, Axis information
VTP	Speed/Position Conversion	Slot, Instruction axis
PTV	Position/Speed Conversion	Slot, Instruction axis

Instruction <sup>*1)</sup>	Description	Instruction Operand <sup>*1)</sup>
STP	Stop	Slot, Instruction axis, Deceleration
SSP	Position Synchronization	Slot, Instruction axis, Step number, Master-axis position, Master-axis setting
SSS	Speed Synchronization	Slot, Instruction axis, Master-axis ratio, Slave-axis ratio, Master-axis setting
POR	Position Override	Slot, Instruction axis, Position
SOR	Speed Override	Slot, Instruction axis, Speed
PSO	Positioning Speed	Slot, Instruction axis, Position, Speed
INCH	Inching	Slot, Instruction axis, Inching amount
SNS	Changing Start Step number	Slot, Instruction axis, Step number
MOF	M code OFF	Slot, Instruction axis
PRS	Present Position Preset	Slot, Instruction axis, Position
EMG	Emergency Stop	Slot, Instruction axis
CLR	Error Reset, Output Disable Annulment	Slot, Instruction axis, Pulse output Enable/Disable
WRT	Parameter / Operation Data Saving	Slot, Instruction axis, Axis information

\*1) In instruction, the slot should be assigned as number '0'.

## Operation Data Range for Positioning

Step Number	Item	Specification	Initial Value	Device Range		Remark
				X-axis	Y-axis	
1	Coordinates	0:Absolute, 1:Relative	Absolute	K5384	K8384	Bit
	Operation Pattern	0:End, 1:Continue, 2:Repeat	End	K5382~3	K8382~3	Bit
	Control Method	0:Position control, 1:Speed control	Position	K5381	K8381	Bit
	Operation Method	0:Single operation, 1:Repeated Operation	Single	K5380	K8380	Bit
	Repeating Step	0~30 ("H" type : 0 ~80)	0	K539	K839	Word
	Targeted Position	-2,147,483,648~2,147,483,647[pulse]	0	K530	K830	Double Word
	M Code Number	0~65,535	0	K537	K837	Word
	Accel/Decel Number	0:Number1, 1:Number2 2:Number3, 3: :Number4	0	K5386	K8386	Bit
				K5387	K8387	Bit
	Operation Speed	1~100,000[pulse/sec]	0	K534	K834	Double Word
	Dwell Time	1~50,000[pulse/sec]	0	K536	K836	Word
2	Same items as Step number 1			K540~549	K840~849	-
3	Same items as Step number 1			K550~559	K850~859	-
4~29	Same items as Step number 1			K560~819	K860~1119	-
30	Same items as Step number 1			K820~829	K1120~1129	-
(Only "H" type)	Coordinates	0:Absolute, 1:Relative	Absolute	K23484	K28484	Bit
	Operation Pattern	0:End, 1:Continue, 2:Repeat	End	K23482~3	K28482~3	Bit
	Control Method	0:Position control, 1:Speed control	Position	K23481	K28481	Bit
	Operation Method	0:Single operation, 1:Repeated Operation	Single	K23480	K28480	Bit

Step Number	Item	Specification	Initial Value	Device Range		Remark
				X-axis	Y-axis	
31 (Only "H" type)	Repeating Step	0~30 ("H" type : 0 ~80)	0	K2349	K2849	Word
	Targeted Position	-2,147,483,648~2,147,483,647[pulse]	0	K2340	K2840	Double Word
	M Code Number	0~65,535	0	K2347	K2847	Word
	Accel/Decel Number	0:Number1, 1:Number2 2:Number3, 3: :Number4	0	K23486 K23487	K28486 K28487	Bit
	Operation Speed	1~100,000[pulse/sec]	0	K2344	K2844	Double Word
	Dwell Time	1~50,000[pulse/sec]	0	K2346	K2846	Word
32	Same items as Step number 31			K2350~23 59	K2850~28 59	"H" type only
33	Same items as Step number 31			K2360~23 69	K2860~28 69	
34~79	Same items as Step number 31			K2370~28 29	K2870~33 29	
80	Same items as Step number 31			K2830~28 39	K3330~333 9	

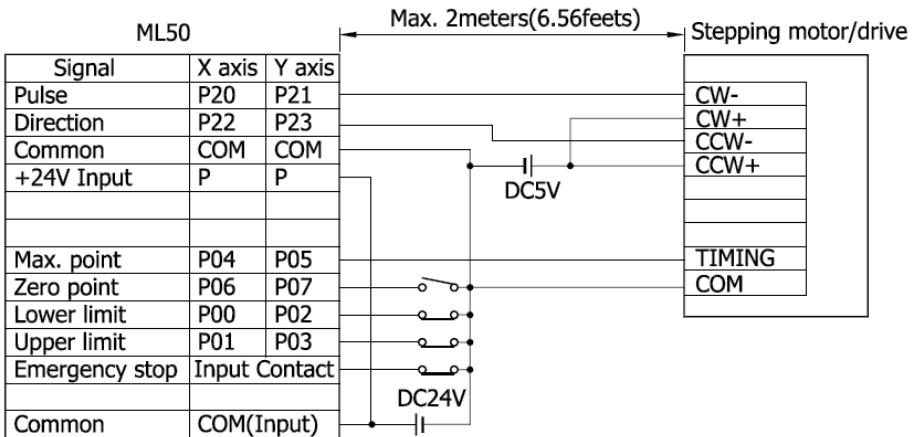
### Operation Monitoring Range for Positioning

Item	Device Range						Remark	
	X axis			Y axis				
	Word	Bit	Address	Word	Bit	Address		
Busy Signal	K420	0	K4200	K430	0	K4300	Operation Monitoring	
ERROR		1	K4201		1	K4301		
Positioning Completed		2	K4202		2	K4302		
M code ON		3	K4203		3	K4303		
Zero Determination		4	K4204		4	K4304		
Output Disable		5	K4205		5	K4305		
Stop		6	K4206		6	K4306		
High Limit Detection		8	K4208		8	K4308		
Low Limit Detection		9	K4209		9	K4309		
Emergency Stop		A	K420A		A	K430A		
Forward/Reverse Rotation		B	K420B		B	K430B		
Operation (Acceleration)		C	K420C		C	K430C		
Operation (Fixed Speed)		D	K420D		D	K430D		
Operation (Deceleration)		E	K420E		E	K430E		
Operation (Dwell)		F	K420F		F	K430F		
Operation Control (Position Control)	K421	0	K4210	K431	0	K4310		
Operation Control (Speed Control)		1	K4211		1	K4311		
Operation Control (Linear Interpolation)		2	K4212		2	K4312		

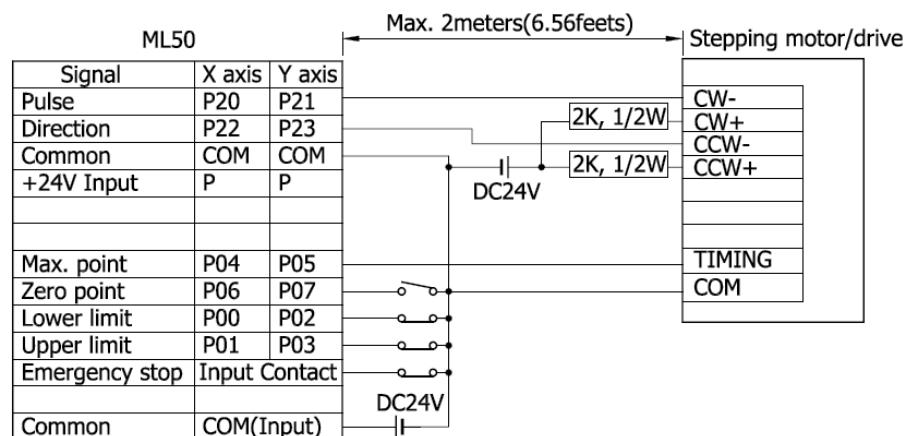
Item	Device Range						Remark	
	X axis			Y axis				
	Word	Bit	Address	Word	Bit	Address		
Zero Return	K421	5	K4215	K431	5	K4315	Operation Monitoring	
Position Synchronization		6	K4216		6	K4316		
Speed Synchronization		7	K4217		7	K4317		
JOG Low Speed		8	K4218		8	K4318		
JOG High Speed		9	K4219		9	K4319		
Inching		A	K421A		A	K431A		
Present Position	K422	-	K422	K432	-	K432	JOG Command	
Present Speed	K424	-	K424	K434	-	K434		
Step Number	K426	-	K426	K436	-	K436		
Error Code	K427	-	K427	K437	-	K437		
M Code	K428	-	K428	K438	-	K438		
JOG Operation (Start)	K429		K4290	K439	0	K4390		
JOG Forward Operation			K4291		1	K4391		
JOG Reverse Operation			K4292		2	K4392		
JOG Low/High Speed			K4293		3	K4393		

### Positioning Function Wiring

- With DC5V



- With DC24V



## Specifications

### PID Control

#### Features

- Built-in PID control function in ML50's main unit
- Various control operation (P, PI, PD, PID, On/Off)
- PWM (Pulse Width Modulation) output of control result
- Forward, Reverse, Forward / Reverse Mixed Operation
- Enhanced response to disturbance with cascade loop
- Available to use 2 set values and PID parameters simultaneously according to operation zone
- Various PID control configurations with its SV Ramp, PV Tracking, Delta MV, MV Preset, Alarm functions

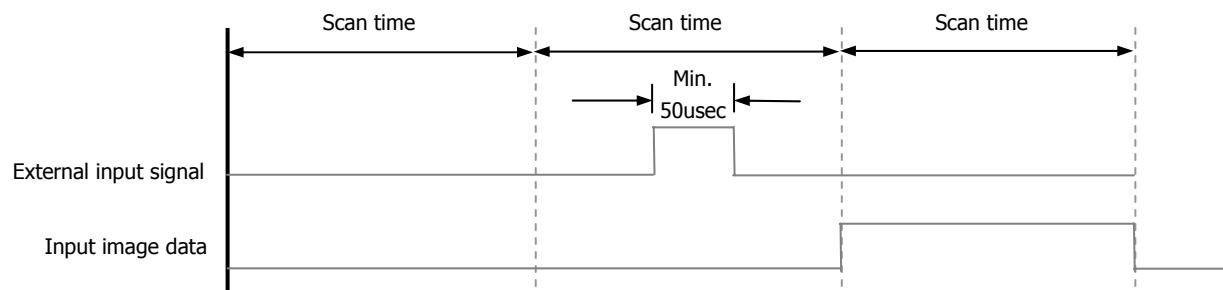
#### Performance

No. of Control Loop	16-loop independent control	
Control Mode	P control, PI control, PD control, PID control	
Control Period	10ms ~ 6563.5 ms (Setting unit: 0.1ms)	
Function	Forward / Reverse Mixed Control	Switching control direction automatically when exceeding dead band
	Cascade	Improved control precision by serial connection between Master loop and Slave loop
	SV Ramp	Preventing overload caused by excessive SV change by setting variation slope
	Alarm	Improved control stability with various alarm function such as MV high limit / low limit, PV high limit / low limit, PV variation width
	Auto Tuning	Auto tuning with improved auto-tuning algorithm
	Additional Function	PWM output, PV tracking, Δ MV, Δ PV, etc.

## Pulse catch / Input Filter / Task

### Pulse Catch

When the On-condition time of input signal (P0000~P0007) is shorter than 1 scan time (Min. 50μs), Pulse catch processes the input signal as normal input.

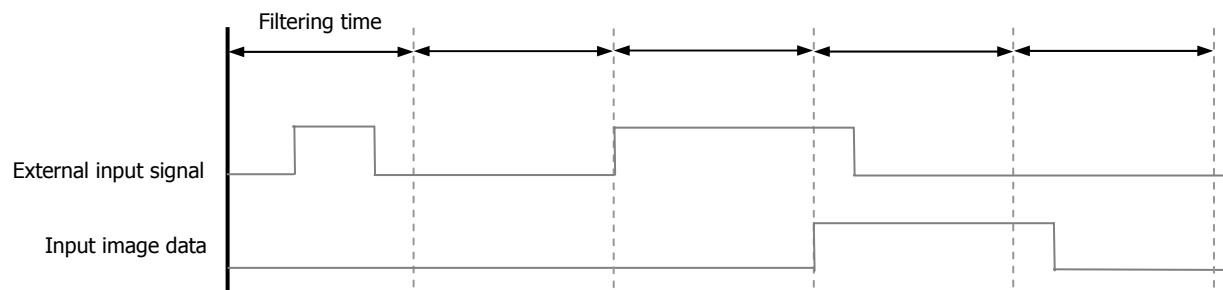


No. of Setting Points	8 points : P000~P007
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Min. Pulse Width	50usec
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### Input Filter

Input filter prevents processing of input signal that is shorter than the filtering time. (Filtering time set by parameter). In the application site where noise is frequently generated. Input filter prevents wrong input caused by noise.



No. of Setting Points	Every input contact
-----------------------	---------------------

Input Filtering Time Setting	Assigning for each module
------------------------------	---------------------------

Setting Range	1-100msec( 1, 3, 5, 10, 20, 70, 100)
---------------	--------------------------------------

### Task

Task function is the processing method of internal / external signal generated periodically (Total 24 Tasks can be assigned). It stops operation of scan program for the moment and then executes the assigned task.

### Types of Task

Initialization Task Setting	Running a task one time before INIT_DONE at initial execution	
Fixed Cycle Task Setting	No. of Setting Points	8 points
	Setting Range	1 ~ 42,94,967,295 msec
External Points Task Setting	No. of Setting Points	8 points: P000 ~ P007
	Minimum Pulse Width	Min. 50usec
	Condition	Up, Down, Change
Internal Device Task Setting	No. of Setting Points	8 points
	Condition	Up, Down, change, On, Off

## Specifications

### Digital Input

Model	MLE-DC08A	MLE-DC16A	MLE-DC32A	
Input points	8	16	32	
Rated input voltage / current	DC24V / 4mA			
Operation voltage range	DC20.4 ~ 28.8V (Ripple rate < 5%)			
Input resistance	5.6kΩ			
Response time	Off -> On On -> Off	1 / 3 / 5 / 10 / 20 / 70 / 100ms (setting by CPU parameter) initial value: 3ms		
Insulation resistance	10MΩ or more by megger			
COMMON method	8 points / COM	16 points / COM	32 points / COM	
Internal current consumption	30mA	40mA	50mA	

### Wiring

MLE-DC08A	MLE-DC16A
<p>Contact number TB1 00 TB2 01 TB3 02 TB4 03 TB5 04 TB6 05 TB7 06 TB8 07 TB9 DC 24V</p>	<p>Contact number TB1 00 TB2 01 TB3 02 TB4 03 TB5 04 TB6 05 TB7 06 TB8 07 TB9 08 TB10 09 TB1 0A TB2 0B TB3 0C TB4 0D TB5 0E TB6 0F TB7 TB8 TB9 TB10 DC 24V</p>
MLE-DC32A	
Note the wiring with Smart Link	

## Specifications

### Digital Open Collector Output (Transistor)

Model	MLE-TN08A	MLE-TN16A	MLE-TN32A
Output points	8	16	32
Rated load voltage	DC12 / 24V		
Load voltage range	DC 10.2V ~ 26.4V		
Max load current	0.2A / 1 point	0.2A / 1 point, 2A / COM	
Off leakage current	0.1mA or less		
Max. voltage drop (On)	DC 0.4V		
Response time	Off -> On	1 ms or less	
	On -> Off	1 ms or less (Rated load, resistive load)	
Insulation resistance	10MΩ or more by megger		
COMMON method	8 points / COM	16 points / COM	32 points / COM
Internal current consumption	40mA	60mA	120mA

## Wiring

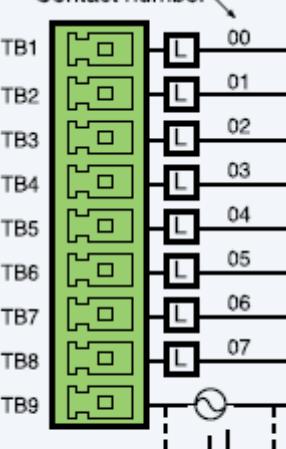
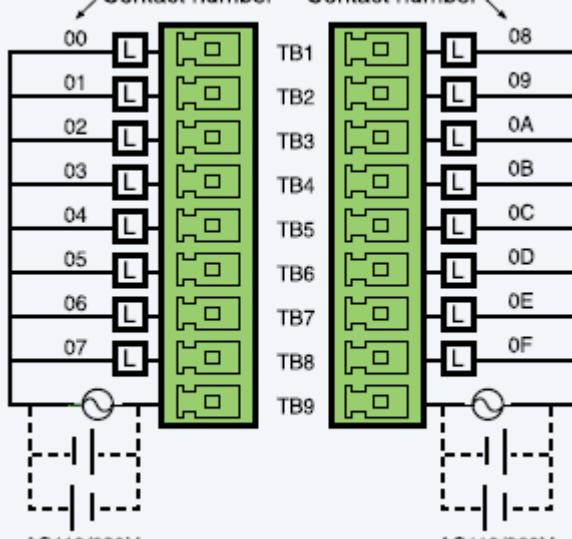
MLE-TN08A	MLE-TN16A	MLE-TN32A
<p>Contact number TB1 00 TB2 01 TB3 02 TB4 03 TB5 04 TB6 05 TB7 06 TB8 07 TB9 TB10</p> <p>DC 12/24V</p>	<p>Contact number 00 01 02 03 04 05 06 07</p> <p>TB1 TB2 TB3 TB4 TB5 TB6 TB7 TB8 TB9 TB10</p>	<p>Contact number 08 09 0A 0B 0C 0D 0E 0F</p> <p>TB1 TB2 TB3 TB4 TB5 TB6 TB7 TB8 TB9 TB10</p> <p>DC 12/24V</p>
Note the wiring with Smart Link		

## Specifications

### Digital Relay Output

Model	MLE-RY08A	MLE-RY16A
Output points	8	16
Insulation method	Relay Insulation	
Rated input voltage / current	DC 24V 2A (resistive load) / AC 220V 2A ( $\text{COS}\Psi = 1$ ), 5A / COM	
Min. load voltage / current	DC 5V 1mA	
Max. load voltage	AC 250V, DC 125V	
Off leakage current	0.1mA (AC 220V, 60Hz)	
Max. on/off frequency	3,600 times / hr	
Surge absorber	None	
Service life	Mechanical	20million times or more
	Electrical	Rated load voltage / current 100,000 times or more
		AC 200V / 1.5A, AC 240V / 1A ( $\text{COS}\Psi = 0.7$ ) 100,000 times or more
		AC 200V / 1A, AC 240V / 0.5 ( $\text{COS}\Psi = 0.35$ ) 100,000 times or more
		DC 24V / 1A, DC 100V / 0.1A ( $L / R = 7\text{ms}$ ) 100,000 times or more
Response time	Off -> On	10ms or less
	On -> Off	12ms or less
COMMON method	8 points / 1COM	
Internal current consumption	230mA	420mA
Operation indicator	Output On, LED On	
External connection method	9-pin terminal block connector	9-pin terminal block connector X 2

### Wiring

MLE-RY08A	MLE-RY16A
<p>Contact number</p>  <p>AC110/220V DC 24V</p>	<p>Contact number</p>  <p>AC110/220V DC 24V</p>

## Specifications

### MLE-DR16A ( Digital input / Relay output)

#### DC Input

Input points	8
Insulation method	Photo coupler
Rated input voltage	DC 24V
Rated input current	4mA
Operation voltage range	DC20.4 ~ 28.8V (Ripple rate < 5%)
On voltage / On current	DC19V or more / 3mA or more
Off voltage / Off current	DC6V or less / 1mA or less
Input resistance	5.6kΩ
Response time	Off -> On On -> Off
COMMON method	8 points / COM
Weight	81g

#### Relay output

Output points	8
Insulation method	Relay Insulation
Rated input voltage / current	DC 24V 2A (resistive load) / AC 220V 2A (COSΨ = 1), 5A /COM
Min. load voltage / current	DC5V 1mA
Max. load voltage	AC250V, DC125V
Off leakage current	0.1mA (AC220V, 60Hz)
Max. on / off frequency	3,600 times / hr
Surge absorber	None
Service life	Mechanical
	20million times or more
	Rated load voltage / current 100,000 times or more
	AC 200V / 1.5A, AC 240V / 1A (COSΨ = 0.7) 100,000 times or more
	AC 200V / 1A, AC 240V / 0.5 (COSΨ = 0.35) 100,000 times or more
Response time	Off -> On
	10ms or less
	On -> Off
COMMON method	8 points / 1COM
Internal current consumption	250mA
Operation indicator	Output On, LED On
External connection method	9-pin terminal block connector

## Wiring

8-point DC input	8-point Relay Output
<p>Contact number</p>	<p>Contact number</p>

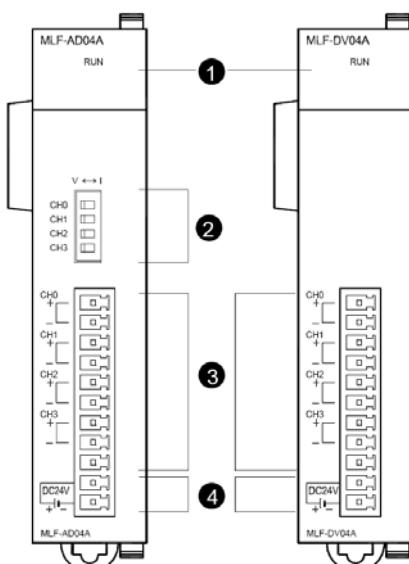
## Specifications

### Analog Input / Output

#### Performance

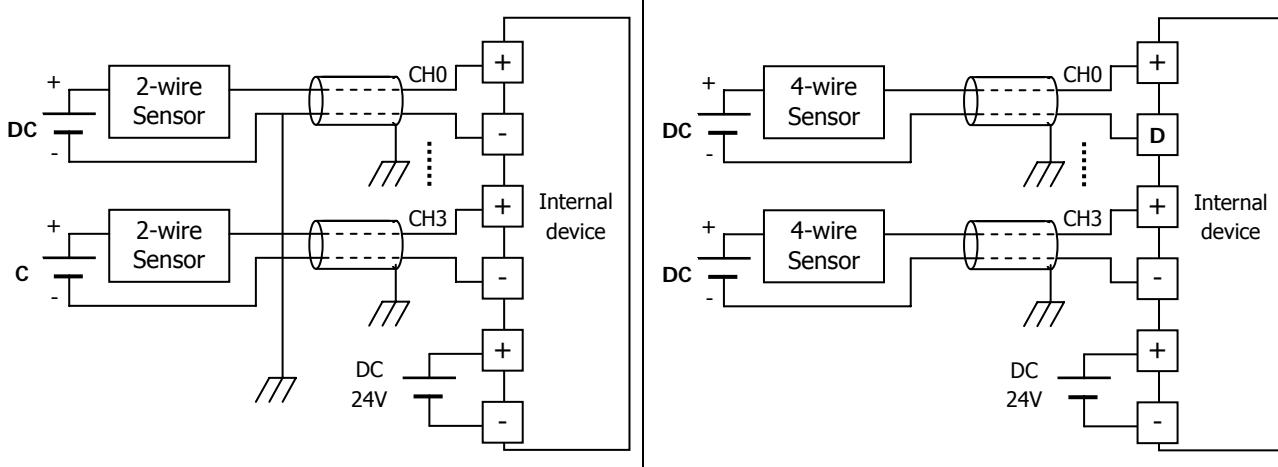
Model	Analog Input			Analog Output
	MLF-AD04A			MLF-DV04A
Analog Range	DC 0 ~ 10V(Input Resistance : 1MΩ min.) DC 4 ~ 20mA DC 0 ~ 20mA(Input Resistance 250Ω)			DC 0 ~10V(Load Resistance ≥ 1kΩ)
Analog Range Selection	- Analog input range can be selected by user (sequence) program - Each input range can be set for each channel.			-
Digital Data	Analog Range	0 ~ 10V	4~20mA	0 ~ 20mA
	Unsigned Value	0 ~ 4000		
	Signed Value	-2000 ~ 2000		
	Precise Value	0 ~ 1000	400 ~ 2000	0 ~ 2000
	Percentile Value	0 ~ 1000		
	Data format of digital output is set by user program of software package. (Setting for each channel is available.)			
Resolution(1/4000)		2.5mV, at 0 ~ 10V		2.5mV
		5.0uA, at 4~20mA or 0~20mA		
Max. Conversion Speed		1.5msec / channel		1msec / channel
Max. Absolute Input / Output		±15V	±25mA	±15V
Accuracy		±0.5% or less		±0.5% or less
Analog I/O Channels		4 channel / module		
Insulation Method		Photo coupler insulation between I/O terminal and power supply.		
Connection Terminal		11-point terminal block		
Occupied I/O Points		Fixed type : 64points		
Current Consumption		DC24V:80mA(External input)		DC24V:200mA(External input)

#### Names and Functions



No	Name	Description
1	RUN LED	Indicates condition of module <ul style="list-style-type: none"> <li>LED ON : Normal condition</li> <li>LED Flicking(ON/OFF) : Error</li> <li>LED OFF : Power off or Module malfunction</li> </ul>
2	Input Selection Switch	Voltage/Current selection terminal <ul style="list-style-type: none"> <li>V : Voltage input selection</li> <li>I : Current input selection</li> </ul>
3	External Connection Terminal	External device connection
4	External Power Supply Terminal	External DC24V input

## Analog Input Wiring



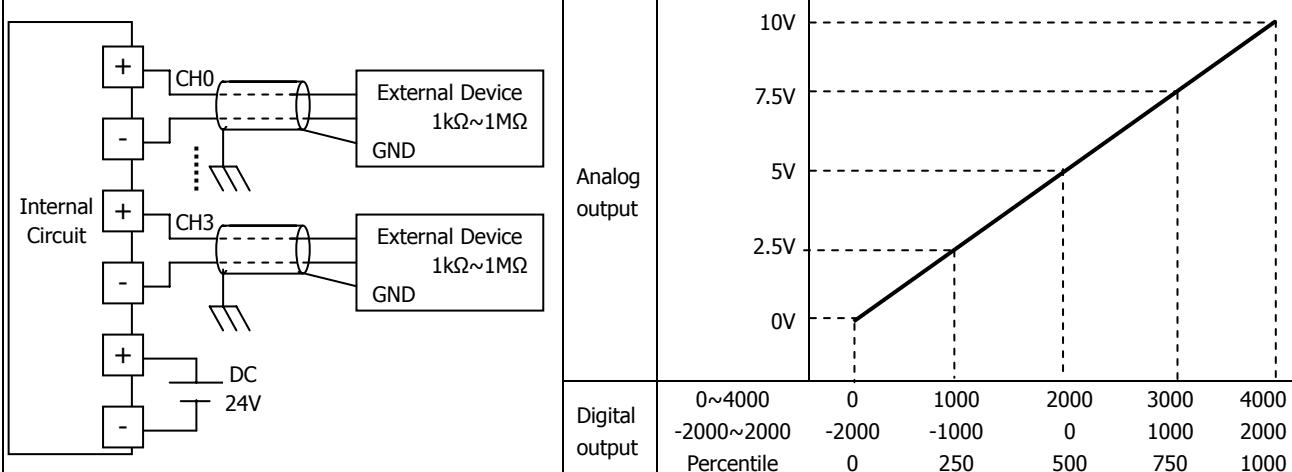
\* Use 22AWG, 2 conductor, twist shield cable when wiring between analog module and external device.

## Analog / Digital Conversion Characteristics (MLF-AD04A)

Output Value Selection	Precise Value			Percentile Value	-2,000	0			
	4~20mA	0~20mA	0~10V		~2,000	~4,000			
Digital Output	2,023	2,023	1,011	1,011	2,047	4,047			
	2,000	2,000	1,000	1,000	2,000	4,000			
	1,600	1,500	750	750	1,000	3,000			
	1,200	1,000	500	500	0	2,000			
	800	500	250	250	-1,000	1,000			
	400	0	0	0	-2,000	0			
Analog Input	381				-2,048	-48			
					*Note1)	*Note1)			
					0	2.5	5	7.5	10
					0	5	10	15	20
					4	8	12	16	20

\* Note1) Supported in case of analog input is 4~20mA.

## Analog Output Wiring



## Specifications

### RTD

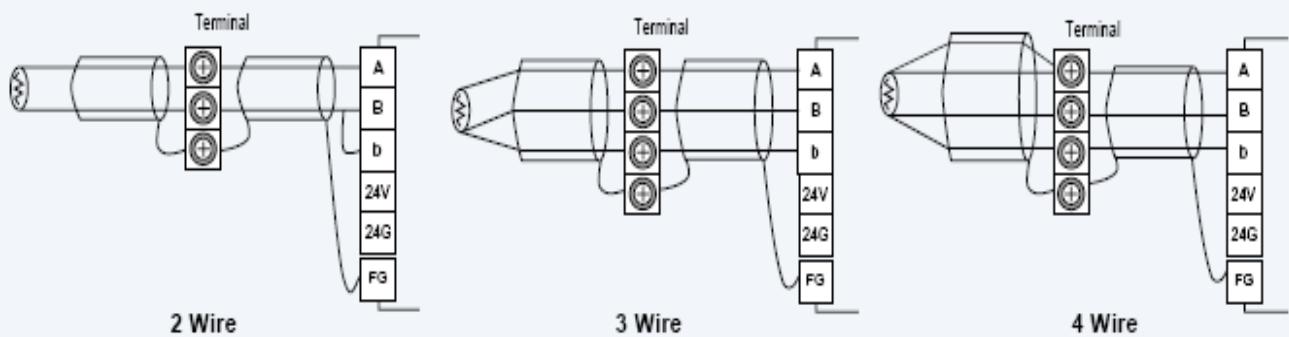
#### Performance

Model	MLF-RD04A	
Number of Channels	4	
Sensor type	PT100	JIS C1804-1997
	JPT100	JIS C1604-1981, KS C1603-1991
Temperature range	PT100	- 200 ~ 600 °C
	JPT100	- 200 ~ 600 °C
Digital output	PT100	- 2000 ~ 6000
	JPT100	- 2000 ~ 6000
Accuracy	25 °C	±0.3% or less
	0 ~ 55 °C	±0.5% or less
Conversion speed	40ms / channel	
Wiring method	3 Wires	
Current consumption	Internal DC5V	100mA
	External DC24V	100mA

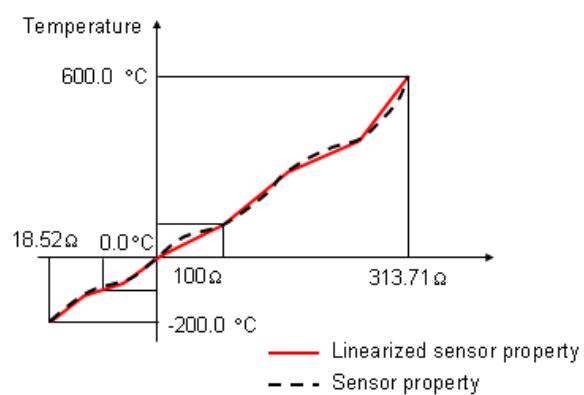
#### Names and Functions

No	Name	Description
1	RUN LED	Displays the hardware operation status (Fatal fault) <ul style="list-style-type: none"> <li>• On: Normal status</li> <li>• Flickering: Error (0.2s flickering)</li> <li>• Off: hardware error or power off</li> </ul>
2	ALARM LED	Displays the status of the channels (Light fault) <ul style="list-style-type: none"> <li>• Flickering: Line disconnection (1s flickering)</li> <li>• Off: Normal status</li> </ul>
3	External Connection Terminal	3-wire RTD sensors can be connected
4	External Power Supply Terminal	External DC24V input
5	Expansion connector	Connects the module with an expansion module

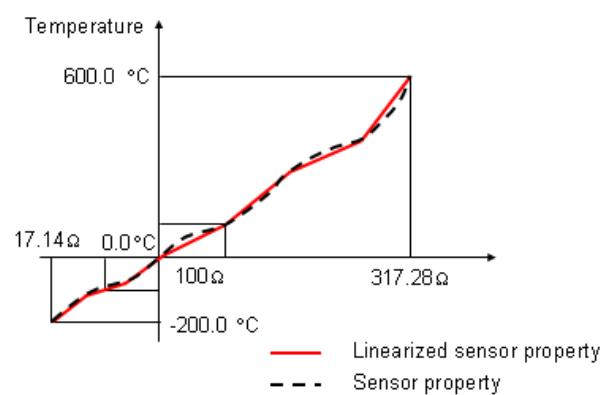
## Analog Input Wiring



## Temperature Conversion Characteristics (MLF-RD04A)



PT100 (JIS1604-1997)



JPT100 (JIS1604-1981, KSC1603-1991)

## Specifications

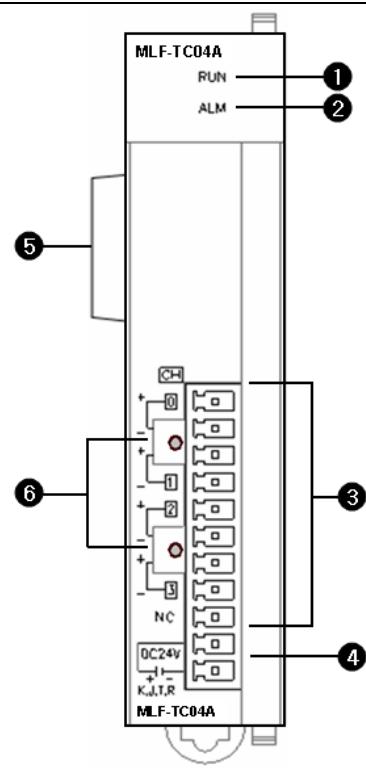
### Thermocouple

#### Performance

Model	MLF-TC04S	
Number of Channels	4	
Sensor type	Thermocouple K / J / T / R JIS C1602-1995	
Temperature range	K	- 200.0°C ~ 1300.0°C (-328.0°F ~ 2372.0°F)
	J	- 200.0°C ~ 1200.0°C (-328.0°F ~ 2192.0°F)
	T	- 200.0°C ~ 400.0°C (-328.0°F ~ 752.0°F)
	R	0.0°C ~ 1700.0°C (32.0°F ~ 3092.0°F)
Digital output	Temperature display unit	Display down to one decimal place K, J, T: 0.1°C R: 0.5°C
	Scaling display (Defined by user)	Unsigned scaling (0 ~ 65535) Signed scaling (-32768 ~ 32767)
	Normal temperature(25°C)	±0.2%
Accuracy	Temperature coefficient (0 ~ 55°C)	±100 ppm / °C
	Conversion speed	50ms / channel
Warming-up time	15 minutes or more	
Terminal	11 point	
I/O points occupied	64 points	
Current consumption	Internal DC5V	100mA
	External DC24V	100mA

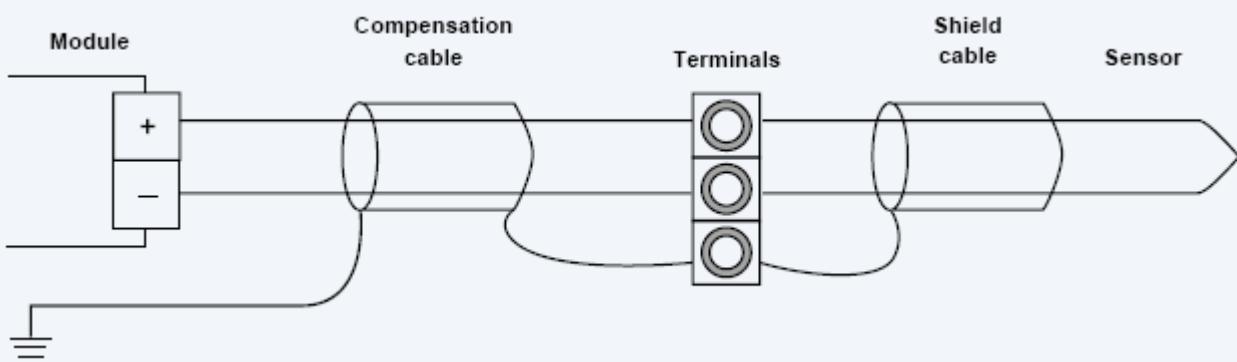
### Names and Functions

No	Name	Description
1	RUN LED	Displays the hardware operation status (Fatal fault) <ul style="list-style-type: none"> <li>On: Normal status</li> <li>Flickering: Error (0.2s flickering)</li> <li>Off: hardware error or power off</li> </ul>
2	ALARM LED	Displays the status of the channels (Light fault) <ul style="list-style-type: none"> <li>Flickering: Line disconnection (1s flickering)</li> <li>Off: Normal status</li> </ul>
3	External Connection Terminal	Connects external thermocouple sensor (K, J, T, R Type)
4	External Power Supply Terminal	External DC24V input
5	Expansion connector	Connects the module with an expansion module
6	Cold junction compensator	Executes reference junction compensation (RJC)



The diagram illustrates the terminal block connections for the MLF-TC04A module. 
 - Pin 1 (RUN) connects to the RUN LED.
 - Pin 2 (ALM) connects to the ALARM LED.
 - Pin 3 connects to the External Connection Terminal for thermocouple sensors.
 - Pin 4 connects to the External Power Supply Terminal for DC24V input.
 - Pin 5 connects to the Expansion connector.
 - Pin 6 connects to the Cold junction compensator.

## Analog Input Wiring



## Accuracy and Resolution

TC type	Temperature input range	Displayed temperature range	Accuracy *Note1)		Resolution
			25°C	0 ~ 50°C *Note2)	
K	-200.0°C ~ 1300.0°C	-270.0°C ~ -200.0°C	*Note3)		
		-200.0°C ~ 0.0°C	±3.0°C	±7.5°C	0.2°C
		0.0°C ~ 1300.0°C	±3.0°C	±7.5°C	0.1°C
		1300.0°C ~ 1372.0°C	*Note3)		
J	-200.0°C ~ 1200.0°C	-210.0°C ~ -200.0°C	*Note3)		
		-200.0°C ~ -100.0°C	±2.8°C	±7.0°C	0.2°C
		-100.0°C ~ 1200.0°C	±2.8°C	±7.0°C	0.1°C
T	-200.0°C ~ 400.0°C	-270.0°C ~ -200.0°C	*Note3)		
		-200.0°C ~ 400.0°C	±1.2°C	±3.0°C	0.1°C
R	0.0°C ~ 1700.0°C	-50.0°C ~ 0.0°C	*Note3)		
		0.0°C ~ 1700.0°C	±3.5°C	±8.5°C	0.5°C
		1700.0°C ~ 1768.0°C	*Note3)		

\* Note 1) Total accuracy(25°C) = Accuracy(25°C) + RJC accuracy  
= ±(Full scale X 0.2% + 1.0°C)

RJC accuracy = ±1.0°C

\* Note 2) Temperature coefficient: ±100 ppm/°C

\* Note 3) In the range, temperature can be measured, but accuracy and resolution are not guaranteed.

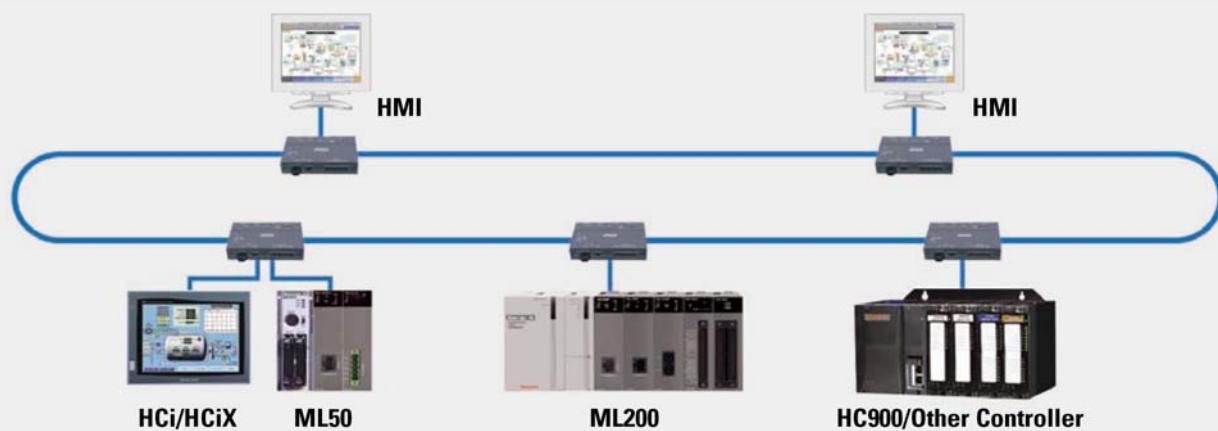
## Specifications

### Communication – Fast Ethernet

#### Features

- 10/100 Base-Tx Fast Ethernet for industrial use (IEEE802.3)
- Dedicated service for HMI connection (Modbus-TCP protocol)
- High speed link communication with high-level PLC(MasterLogic-200, MasterLogic-200IEC)
- Remote program, Remote monitoring with SoftMaster remote service
- Network security with Host table(limitation of unwanted connections)
- Convenient network system setting and various self-diagnosis / monitoring with SoftMaster-NM
  - Monitoring network information (Auto scan)
  - Checking module in network (PING)
  - Providing information of each service  
(High speed link, P2P, dedicated service, media condition)
- User protocol editing and P2P service (Communication with other brand's equipment)

#### Network with Ethernet



#### Performance

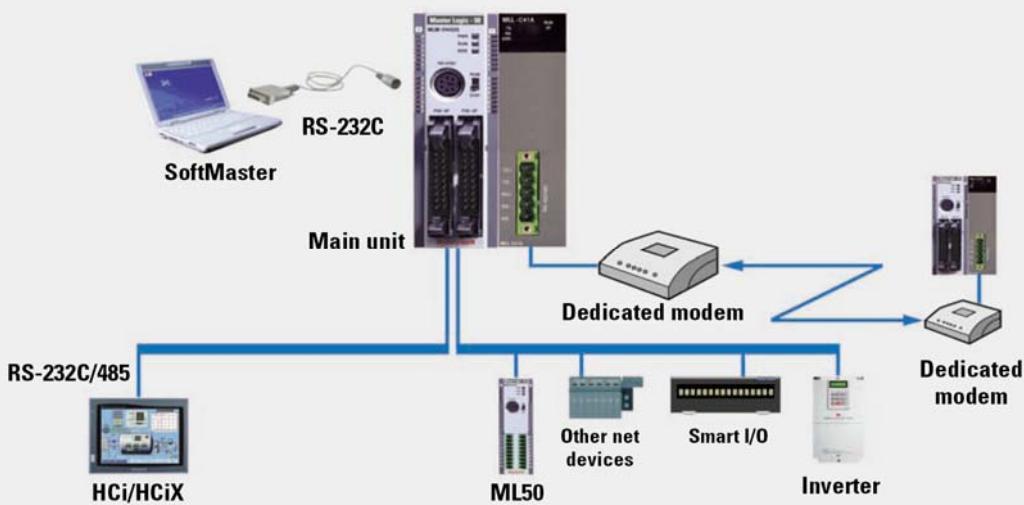
Model	MLL-EMTA	
Communication Spec.	10/100 Base-TX	
Protocol	TCP/IP, UDP/IP	
Service	With ML PLCs	High-speed link, P2P service
	With Other Devices	P2P service
	Application	Dedicated protocol service, SoftMaster Service
HS Link Sending / Receiving	200 words / block(Max. 128 blocks)	
No. of Channel Connectable to Upper Stage	8 channels	
Service	Communication with PC (HMI) and external devices, high-speed communication among ML PLC's	
Media	UTP/STP Category 5	
Current Consumption(mA)	410	

## Communications – Snet

### Features

- Max. 2 modules mountable for 1 main unit. Total 5 channels of communication in 1 MasterLogic-50 system(including Loader)
- Max. 32-unit connection through RS-485 communication.
- Protocol editing and parameter setting using SoftMaster-NM.
- Configurable communication speed setting (300 ~ 115,200 bps)
- Long distance communication system using dedicated modem (expansion RS-232C Communication module)
- Full duplex / Half Duplex communication (expansion RS485 Communication module)
- PTP : User-defined Communication and Modbus communication master
- Modbus RTU / ASCII drivers for HMI connection
- Various diagnosis function using SoftMaster-NM (I/O information, CPU, Link, Service, LOG)
- Simultaneous monitoring of sending / receiving frame and checking the result of frame
- Communication service information (Checking information of dedicated service, P2P service)

### System Configuration



### Performance

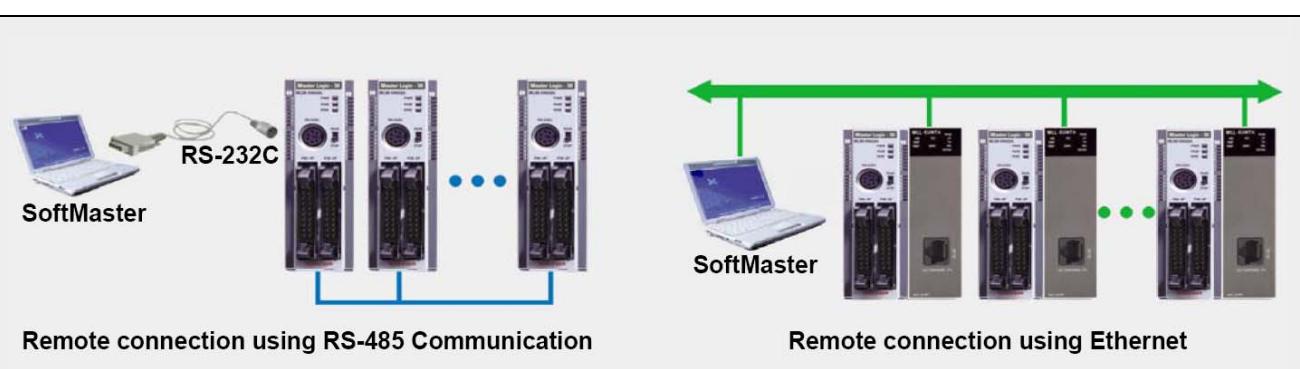
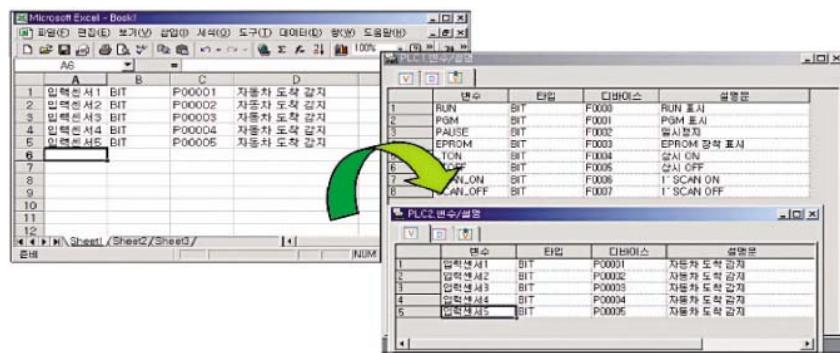
Model	Built-in RS-232C	MLL-CU21A	Built-in RS485	MLL-CU41A			
Interface	RS-232C 1Ch	RS-232C 1Ch	RS-485 1Ch	RS-422/485 1 Ch			
Modem Connection	Remote communication with external devices via modem connection, Available for only RS-232C port.						
Comm. Mode	Dedicated Mode	1:1 or 1:N communication using ML dedicated protocol					
	SoftMaster	Program upload / download and remote control					
	P2P Mode	Communication by protocol using SoftMaster-NM (Interface with other PLC's), HMI, Modbus RTU / ASCII master communication					
Operation Mode	Server(Slave)	Remote connection simultaneously using Modbus server, user-defined					
	Master	Modbus RTU / ASCII master, user defined					
Data Type	Start bit	1					
	Data bit	7 or 8					
	Stop bit	1 or 2					
	Parity	Even / Odd / None					
	Setting	Basic parameter setting with SoftMaster-NM					
Synchronization	Asynchronous						
Transmission Speed(bps)	Selectable 1200 / 2400 / 4800 / 9600 / 19200 / 38400 / 57600 / 115200 bps						

Station Number Setting	Up to 32 stations, from 0 to 31 with SoftMaster-NM			
Transmission Distance	Max.15meters (49.21 feet), extended using modem			Max.500meters (1640.42 feet)
Modem Communication	Not available	Available	Not available	Not available
Network Configuration	1:1			1:N
Diagnosis Function	Available through LED and SoftMaster-NM diagnosis service			
Max. Number of Installation	Built-in	2	Built-in	2

Software
<b>Programming Software SoftMaster</b> <ul style="list-style-type: none"> <li>- Programming editing &amp; engineering software</li> <li>- Windows based easy operation</li> <li>- Multi-PLC, Multi-programming supports</li> <li>- Various monitoring and diagnosis functions</li> <li>- Windows 2000, XP (Limited use in Windows 98, ME version)</li> </ul>
<p>The diagram illustrates the monitoring capabilities of the SoftMaster system. It shows a central 'Network scan' interface connected to multiple monitoring modules: 'Device monitoring' (displaying a rack of modules), 'Frame monitoring' (displaying network frames), 'User event' (displaying a table of events), 'Special Module monitoring' (displaying module status), and 'Table monitoring' (displaying a grid of data).</p>
<b>Network setting</b> <ul style="list-style-type: none"> <li>- Convenient network setting</li> <li>- Extended monitoring function for network system and communication modules</li> <li>- Fast interface with CPU by effective network management</li> <li>- Various built-in diagnosis functions (CPU condition, Link condition, Service condition, Auto scan, LOG, Frame monitoring)</li> </ul>
<p>The diagram shows the network architecture and monitoring points. A 'Fast Ethernet' backbone connects a 'Parameter setting' station, a 'Network scan' station, and a 'Link monitoring' station. Below the backbone, an 'HCI / HCIX' station is connected to an 'Other PLC'. A 'Snet' backbone connects an 'Other net device', a 'Smart I/O' module, and a 'Service condition monitoring' station. Monitoring stations include 'Frame monitoring' and 'Service condition monitoring'.</p>

## Programming Environment

- Cell type input window
- Cell-unit editing
- Auto filling
- Compatibility with Microsoft EXCEL
- Redo & Undo
- Screen split editing
- Drag & Drop – Supports Drag & Drop for project, Variable / Statement, Ladder editing, Variable monitoring
- User defined shortcut key – Enhances user convenience with user-defined shortcut key
- Remote connection with RS-485 communication & Ethernet
- Remote connection with Max. 32 main units using built-in RS485 Communication



## Monitoring

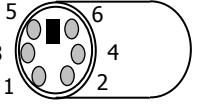
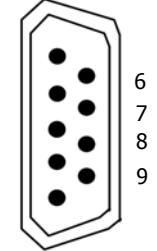
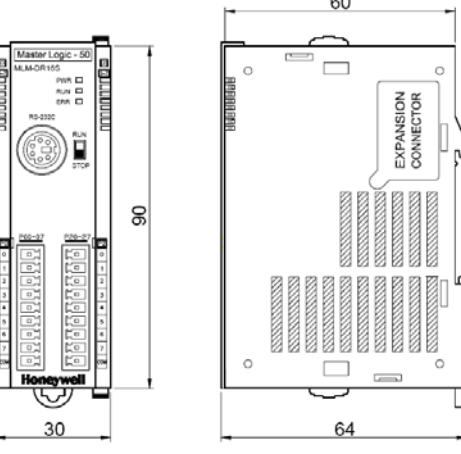
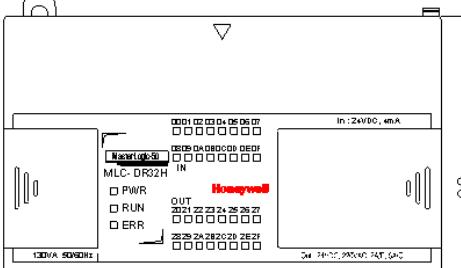
User Defined Events	Trend Monitoring
<p>By registering user-defined events, users can read the record of specified event and user it for PLC operation and debugging.</p>	<p>The progressive / changing value can be monitored and saved as a file.</p>
Device Monitoring	Variable Monitoring

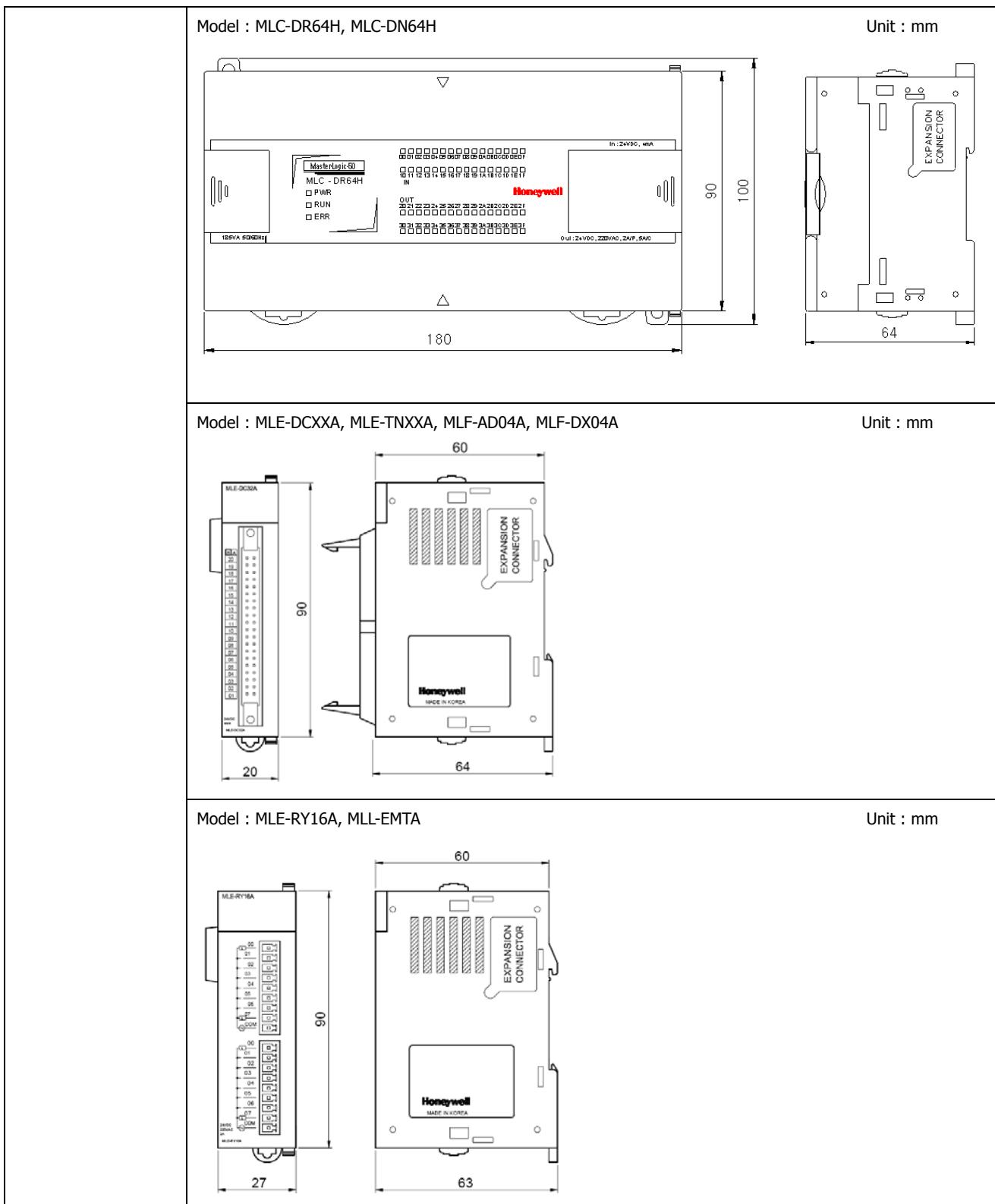
System Requirement	
O/S	Windows 2000, XP (Limited use in Windows 98, ME)
CPU	IBM Compatible PC with Min. 200 MHz Pentium Processor
Memory	Min. 128 Mbytes RAM
HDD	100 MB(Free Memory space)
Serial Port	Communication port for program transmission (RS-232C)
Printer	Compatible with Windows 98 or later
Mouse	Compatible with Windows 98 or later

Product List / Dimension			
Product List			
Item	Model	Specification	Remark
Base Module	MLM-DR16S	DC24V power supply, DC24V input 8 points, Relay output 8 points	SoftMaster V2.2 or more
	MLM-DN16S	DC24V power supply, DC24V input 8 points, open collector output 8 points, built-in positioning function	
	MLM-DN32S	DC24V power supply, DC24V input 16 points, open collector output 16 points, built-in positioning function	
	MLC-DR32H	AC110~220V power supply, DC24V input 16 points, Relay output 16 points, RTC function	
	MLC-DN32H	AC110~220V power supply, DC24V input 16 points, open collector output 16 points, built-in positioning function, RTC function	
	MLC-DR64H	AC110~220V power supply, DC24V input 32 points, Relay output 32 points, RTC function	
	MLC-DN64H	AC110~220V power supply, DC24V input 32 points, open collector output 32 points, built-in positioning function, RTC function	
Expansion I/O Module	MLE-DC08A	DC24V input 8 points	
	MLE-DC16A	DC24V input 16 points	
	MLE-DC32A	DC24V input 32 points	
	MLE-RY08A	Relay output 8 points	
	MLE-RY16A	Relay output 16 points	
	MLE-TN08A	Open collector output 8 points(NPN output)	
	MLE-TN16A	Open collector output 16 points(NPN output)	
	MLE-TN32A	Open collector output 32 points(NPN output)	
	MLE-DR16A	DC24V input 8 points, Relay output 8 points	
Expansion Special Module	MLF-AD04A	Current / Voltage input 4 channel	
	MLF-DC04A	Current output 4 channel	
	MLF-DV04A	Voltage output 4 channel	
	MLF-RD04A	RTD input 4 channel	
	MLF-TC04S	Thermocouple input 4 channel	

Expansion Comm. Module	MLL-CU21A	Snet (RS-232C, Modem)	
	MLL-CU41A	Snet (RS422/485)	
	MLL-EMTA	Ethernet interface	
Software	SoftMaster	Engineering software	
Loader Cable	PMC-310S	Connection Cable (PC to PLC), 9 pin (PC) – 6 pin (PLC), soft tube type cable.	Soft tube type

\* 64-point I/O and Open Collector (PNP) output modules are under development.(MLE-DC64A, TN64A, TP8A, TP16A, TP32A, TP64A)

Loader Cable Connection	<p>ML50(6Pin, Male)</p>  <table border="1"> <tr><td>5</td><td>6</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>1</td><td>2</td></tr> </table> <p>PC(9Pin, Female)</p>  <table border="1"> <tr><td>6</td></tr> <tr><td>2</td></tr> <tr><td>3</td></tr> <tr><td>5</td></tr> <tr><td>1</td></tr> <tr><td>2</td></tr> <tr><td>3</td></tr> <tr><td>4</td></tr> <tr><td>5</td></tr> </table>	5	6	3	4	1	2	6	2	3	5	1	2	3	4	5	
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Dimension	<p>Model : MLM-DN16/32S, MLM-DR16S</p> 	Unit : mm															
	<p>Model : MLC-DR32H, MLC-DN32H</p> 	Unit : mm															



## Model Interpretation

# MasterLogic 50 Logic Controller Assemblies

SPECIFICATIONS	MODEL NUMBER	AVAILABILITY
<b>BASE MODULE (CPU + PWR SUPPLY + BASE I/O)</b>		
DC24V PWR Supply, DC24V Input (8 ch) & Relay Output (8 ch)	(Note 1)	MLM-DR16S
DC24V PWR Supply, DC24V Input (8 ch) & Open Collector Output (8 ch)	(Note 1)	MLM-DN16S
DC24V PWR Supply, DC24V Input (16 ch) & Open Collector Output (16 ch)	(Note 1)	MLM-DN32S
AC110~220V PWR Supply, DC24V input (16 ch) & Open Collector Output (16 ch)	(Note 1)	MLC-DN32H
AC110~220V PWR Supply, DC24V input (32 ch) & Open Collector Output (32 ch)	(Note 1)	MLC-DN64H
AC110~220V PWR Supply, DC24V input (16 ch) & Relay Output (16 ch)	(Note 1)	MLC-DR32H
AC110~220V PWR Supply, DC24V input (32 ch) & Relay Output (32 ch)	(Note 1)	MLC-DR64H
<b>DIGITAL INPUT EXPANSION</b>		
DC24V Input (8 ch)	MLE-DC08A	•
DC24V Input (16 ch)	MLE-DC16A	•
DC24V Input (32 ch)	MLE-DC32A	•
<b>DIGITAL OUTPUT EXPANSION</b>		
Relay Output (8 ch)	MLE-RY08A	•
Relay Output (16 ch)	MLE-RY16A	•
Open Collector Output (8 ch)	MLE-TN08A	•
Open Collector Output (16 ch)	MLE-TN16A	•
Open Collector Output (32 ch)	MLE-TN32A	•
<b>DIGITAL INPUT / OUTPUT EXPANSION</b>		
DC24V Input (8 ch) & Relay Output (8 ch)	MLE-DR16A	•
<b>ANALOG INPUT EXPANSION</b>		
Current/Voltage Input (4 ch)	MLF-AD04A	•
RTD Input (4 ch)	MLF-RD04A	•
TC Input (4 ch)	MLF-TC04A	•
<b>ANALOG OUTPUT EXPANSION</b>		
Current Output (4 ch)	MLF-DC04A	•
Voltage Output (4 ch)	MLF-DV04A	•
<b>COMMUNICATION EXPANSION</b>		
RS-232C/Modem (MLDP)	MLL-CU21A	•
RS-422/485 (MODBUS RTU/ASC II, MLDP)	MLL-CU41A	•
Ethernet (TCP/IP, UDP/IP)	MLL-EMTA	•
<b>MANUAL &amp; ACCESSORY</b>		
ML50 Product Manuals (Full Document Set - Hard Copy, English)	(Note 2)	MLM-00422
Loader Cable		PMC-310S
Smart Link Terminal Board 40 pins		SLP-T40P
Smart Link Cable Ass'y 20x2-40P, 0.5 Meter	(Note 3)	SLT-CT051-XBM
Smart Link Cable Ass'y 20x2-40P, 1.0 Meter	(Note 3)	SLT-CT101-XBM
Smart Link Cable Ass'y 40-40P, 1.5 Meter	(Note 4)	SLT-CT151-XBE
Smart Link Cable Ass'y 40-40P, 3.0 Meter	(Note 4)	SLT-CT301-XBE

**Note 1:** Documentation is not provided with this model. If required, order the item separately.

**Note 2:** The manual set contains all ML50 product manuals. Documentation is available only in English language.

**Note 3:** The cable is used for the remote wiring of the Base Module MLM-DN32S and MLM-DN16S.

**Note 4:** The cable is used for the remote wiring of the DI/O Expansion Module MLE-TN32A / MLE-DC32A only.

## **Warranty / Remedy**

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship. Contact your local sales office for warranty information. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace without charge those items it finds defective. The foregoing is Buyer's sole remedy and is **in lieu of all other warranties, expressed or implied, including those of merchantability and fitness for a particular purpose**. Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this printing. However, we assume no responsibility for its use. While we provide application assistance personally, through our literature and the Honeywell web site, it is up to the customer to determine the suitability of the product in the application.

*Specifications are subject to change without notice.*

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